



16-Channel Constant Current LED Sink Driver with Error Detection and Current Gain

Features

- 16 constant-current output channels
Constant output current range: 3~90mA
 - 8-90mA @ 5V supply voltage
 - 3-70mA @ 3.3V supply voltage
- In-message error detection
 - Both open-circuit and short-circuit LEDs can be detected
 - On-the-fly error detection
 - Data-in, error-out; both errors are merged and coded with zeros
- Compulsory error detection
 - Full panel, data independent
 - Silent error detection with 0.1mA in 500ns
- Settable threshold voltage for LED short-circuit detection
- Thermal detection
 - Over-temperature report (e.g. temp.>150 °C)
- 64-step programmable current gain: from 12.5% to 200%
- Excellent output current accuracy,
 - Between channels: $\pm 1.5\%$ (typ.), and
 - Between ICs: $\pm 3\%$ (typ.)
- Fast response of output current
 - Min. output pulse width of \overline{OE} :
35ns with good uniformity between output channels
- Staggered delay of output, preventing from current surge
- 30MHz clock frequency
- Schmitt trigger input



Product Description

MBI5039 is an enhanced 16-channel constant current LED sink driver with smart error detection and output current gain. MBI5039 succeeds MBI5026 and also exploits **PrecisionDrive™** technology to enhance the output characteristics. Furthermore, MBI5039 adopts **Share-I-O™** technology to be backward compatible with MBI5026, MBI5027 and MBI5029 in pin definition and to extend the functionality for LED's in-message error detection, compulsory error detection, and current gain control in LED display systems.

MBI5039 contains a 16-bit shift register and a 16-bit output latch, which convert serial input data into parallel output format. At MBI5039 output stages,

sixteen regulated current ports are designed to provide uniform and constant current sinks with small skew between ports for driving LEDs within a wide range of forward voltage (V_F) variations. Users may adjust the output current from 5mA to 90mA with an external resistor R_{ext} , which provides users flexibility in controlling the light intensity of LEDs. MBI5039 guarantees to endure maximum 17V at the output ports. Besides, the high clock frequency, up to 30MHz, also satisfies the system requirements of high volume data transmission.

With in-message error detection, MBI5039 can detect individual LED for both open- and short-circuit errors

on-the-fly without extra components. The serial data could be transferred into MBI5039 via the pin SDI, shifted in the shift register, and the outputs perform open- and short-circuit detection simultaneously.

Besides the default in-message error detection, MBI5039 provides compulsory error detection. Once the dedicated command is issued, all of the output ports will be turned on about 500ns interval with current 0.1mA. Since the turn-on duration and current are so small, the image quality will not be impacted. All of the channels are detected no matter the input data is zero or one. The dedicated command is the communication of CLK and LE.

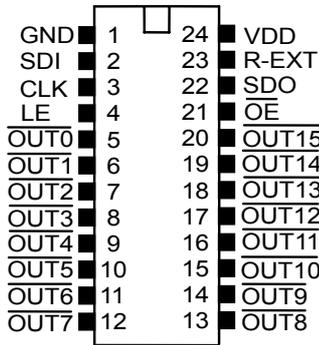
With the above two detections, the system can detect LED errors completely. Moreover, the threshold voltage for short-circuit detection is settable with the variation of different LED forward voltage, and the system controller can easily detect the short-circuit error. Therefore, the error detection is easy to use.

In addition, MBI5039 also allows users to adjust the output current level by setting a programmable configuration code. The code is sent into MBI5039 via the pin SDI. The falling edge of LE would latch the code in the shift register into a built-in 16-bit configuration register, instead of the output latch. The gain code would affect the voltage at the terminal R-EXT and control the output current regulator. The output current can be adjusted finely by a gain ranging from 12.5% to 200% in 64 steps.

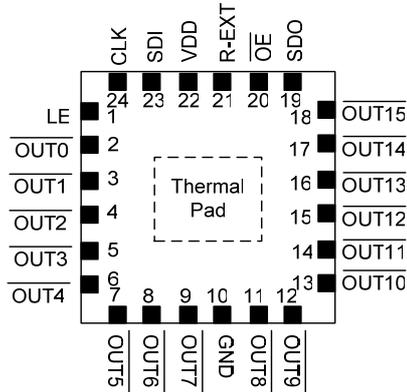
The temperature of the chip itself is also monitored and the thermal warning flag can be read so that the system can adopt essential procedure to protect the system.

With the **Share-I-O™** technique, MBI5039 could be a drop-in replacement of predecessors. The printed circuit board originally designed for MBI5026/7/9 may be also applied to MBI5039 only that the controllers have to be upgraded and \overline{OE} needs to be controllable.

Pin Configuration



MBI5039GF/GP

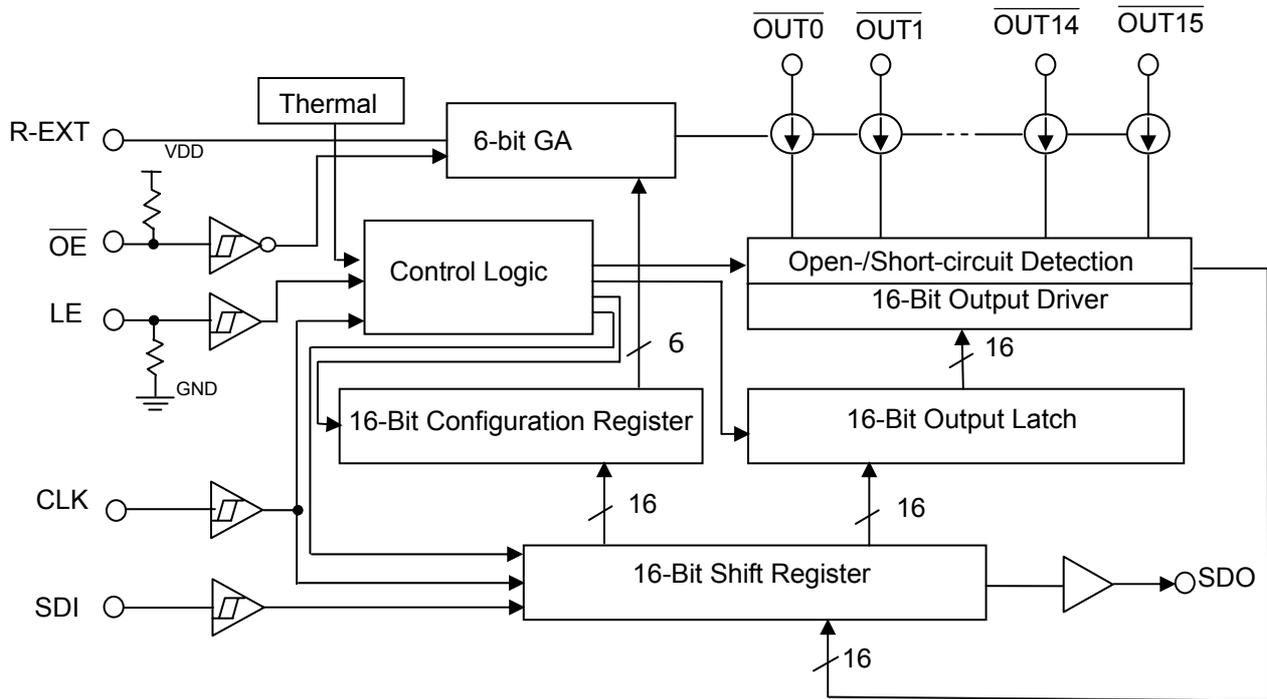


MBI5039GFN

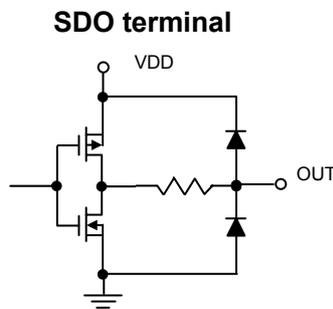
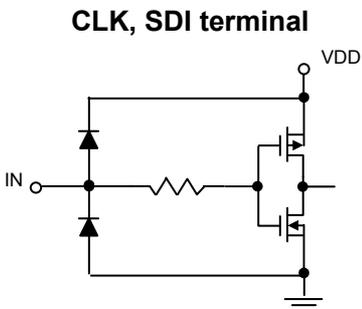
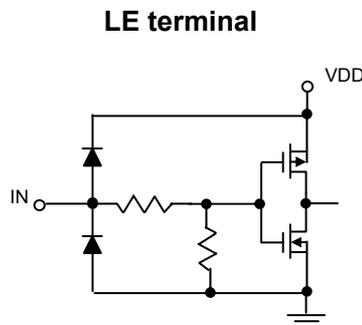
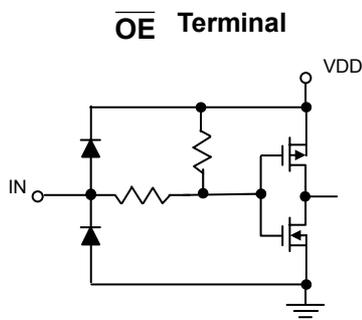
Terminal Description

Pin Name	Function
GND	Ground terminal for control logic and current sinks
SDI	Serial-data input to the shift register
CLK	Clock input terminal used to shift data on rising edge and carries command information when LE is asserted.
LE	Data strobe terminal and asserting command with adequate CLK pulses
OUT0 ~ OUT15	Constant current output terminals
OE	Enable output drivers to sink current. When its level is low (active), the output drivers are enabled; when high, all output drivers are turned OFF (blank). The signal is used for error detection. Please refer to error detection sections for further details.
SDO	Serial-data output to the SDI of the following driver IC
R-EXT	Input terminal used for connecting an external resistor in order to set up the current level of all output ports
VDD	3.3/5V supply voltage terminal

Block Diagram



Equivalent Circuits of Inputs and Outputs



Maximum Ratings

Characteristic		Symbol	Rating	Unit
Supply Voltage		V_{DD}	7	V
Input Pin Voltage (SDI, \overline{OE} , LE, CLK)		V_{IN}	-0.4~ V_{DD} +0.4	V
Output Current ($\overline{OUT0}$ ~ $\overline{OUT15}$)		I_{OUT}	+100	mA
Sustaining Voltage at OUT Port		V_{DS}	17	V
GND Terminal Current		I_{GND}	+1440	mA
Power Dissipation (On PCB, $T_a=25^\circ\text{C}$)	GF Type	P_D	2.51	W
	GP Type		2.04	
	GFN Type		3.19	
Thermal Resistance (On PCB, $T_a=25^\circ\text{C}$)	GF Type	$R_{th(j-a)}$	49.86	$^\circ\text{C/W}$
	GP Type		61.20	
	GFN Type		39.15	
Operating Temperature		T_{opr}	-40~+85	$^\circ\text{C}$
Storage Temperature		T_{stg}	-55~+150	$^\circ\text{C}$
ESD Rating	HBM (MIL-STD-883G Method 3015.7, Human Body Mode)	-	7000	V
	MM (JEDEC EIA/JESD22-A115, Machine Mode)	-	300	V

Electrical Characteristics (V_{DD}=5.0V)

Characteristics		Symbol	Condition	Min.	Typ.	Max.	Unit
Supply Voltage		V _{DD}	-	4.5	5.0	5.5	V
Sustaining Voltage at OUT Ports		V _{DS}	$\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$	-	-	17.0	V
Output Current		I _{OUT}	Refer to "Test Circuit for Electrical Characteristics"	8	-	90	mA
		I _{OH}	SDO	-	-	-1.0	mA
		I _{OL}	SDO	-	-	1.0	mA
Input Voltage	"H" level	V _{IH}	Ta=-40~85°C	0.7xV _{DD}	-	V _{DD}	V
	"L" level	V _{IL}	Ta=-40~85°C	GND	-	0.3xV _{DD}	V
Output Leakage Current		I _{OH}	V _{DS} =17.0V and channel off	-	-	0.5	µA
Output Voltage	SDO	V _{OL}	I _{OL} =+1.0mA	-	-	0.4	V
		V _{OH}	I _{OH} =-1.0mA	4.6	-	-	V
Current Skew (Channel)		dI _{OUT1}	I _{OUT} =20mA V _{DS} =1.0V R _{ext} =700Ω	-	±1.5	±3.0	%
Current Skew (IC)		dI _{OUT2}	I _{OUT} =20mA V _{DS} =1.0V R _{ext} =700Ω	-	±3.0	±6.0	%
Output Current vs. Output Voltage Regulation*		%/dV _{DS}	V _{DS} within 1.0V and 3.0V, R _{ext} =700Ω@20mA	-	±0.1	±0.3	% / V
Output Current vs. Supply Voltage Regulation*		%/dV _{DD}	V _{DD} within 4.5V and 5.5V	-	±1.0	±2.0	% / V
LED Open Detection Threshold Voltage**		V _{OD,TH}	-	-	0.3	0.35	V
Pull-up Resistor		R _{IN(up)}	$\overline{\text{OE}}$	250	450	800	KΩ
Pull-down Resistor		R _{IN(down)}	LE	250	450	800	KΩ
Supply Current	"Off"	I _{DD(off) 1}	R _{ext} =Open, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	2.2	-	mA
		I _{DD(off) 2}	R _{ext} =700Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	5.4	-	
		I _{DD(off) 3}	R _{ext} =230Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	8.5	-	
	"On"	I _{DD(on) 1}	R _{ext} =700Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =On,	-	5.9	-	
		I _{DD(on) 2}	R _{ext} =230Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =On,	-	9.3	-	
Thermal Flag Temperature		T _{TF}	Junction Temperature	135	150	165	°C

*One channel on.

**LED short detection threshold voltage (V_{SD,TH}) is a configurable voltage. Please see the "Definition of Configuration Register" for details.

Electrical Characteristics (V_{DD}=3.3V)

Characteristics		Symbol	Condition	Min.	Typ.	Max.	Unit
Supply Voltage		V _{DD}	-	3.0	3.3	3.6	V
Sustaining Voltage at OUT Ports		V _{DS}	$\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$	-	-	17.0	V
Output Current		I _{OUT}	Refer to "Test Circuit for Electrical Characteristics"	3	-	70	mA
		I _{OH}	SDO	-	-	-1.0	mA
		I _{OL}	SDO	-	-	1.0	mA
Input Voltage	"H" level	V _{IH}	Ta=-40~85°C	0.7xV _{DD}	-	V _{DD}	V
	"L" level	V _{IL}	Ta=-40~85°C	GND	-	0.3xV _{DD}	V
Output Leakage Current		I _{OH}	V _{DS} =17.0V and channel off	-	-	0.5	μA
Output Voltage	SDO	V _{OL}	I _{OL} =+1.0mA	-	-	0.4	V
		V _{OH}	I _{OH} =-1.0mA	2.9	-	-	V
Current Skew (Channel)		dI _{OUT1}	I _{OUT} =20mA V _{DS} =1.0V R _{ext} =700Ω	-	±1.5	±3.0	%
Current Skew (IC)		dI _{OUT2}	I _{OUT} =20mA V _{DS} =1.0V R _{ext} =700Ω	-	±3.0	±6.0	%
Output Current vs. Output Voltage Regulation*		%/dV _{DS}	V _{DS} within 1.0V and 3.0V, R _{ext} =700Ω@20mA	-	±0.1	±0.3	% / V
Output Current vs. Supply Voltage Regulation*		%/dV _{DD}	V _{DD} within 3.0V and 3.6V	-	±1.0	±2.0	% / V
LED Open Detection Threshold Voltage**		V _{OD,TH}	-	-	0.3	0.35	V
Pull-up Resistor		R _{IN(up)}	$\overline{\text{OE}}$	250	450	800	KΩ
Pull-down Resistor		R _{IN(down)}	LE	250	450	800	KΩ
Supply Current	"Off"	I _{DD(off) 1}	R _{ext} =Open, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	1.8	-	mA
		I _{DD(off) 2}	R _{ext} =700Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	5.0	-	
		I _{DD(off) 3}	R _{ext} =230Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =Off,	-	8.0	-	
	"On"	I _{DD(on) 1}	R _{ext} =700Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =On,	-	5.3	-	
		I _{DD(on) 2}	R _{ext} =230Ω, $\overline{\text{OUT0}} \sim \overline{\text{OUT15}}$ =On,	-	8.4	-	
Thermal Flag Temperature		T _{TF}	Junction Temperature	135	150	165	°C

*One channel on.

**LED short detection threshold voltage (V_{SD,TH}) is a configurable voltage. Please see the "Definition of Configuration Register" for details.

Test Circuit for Electrical Characteristics

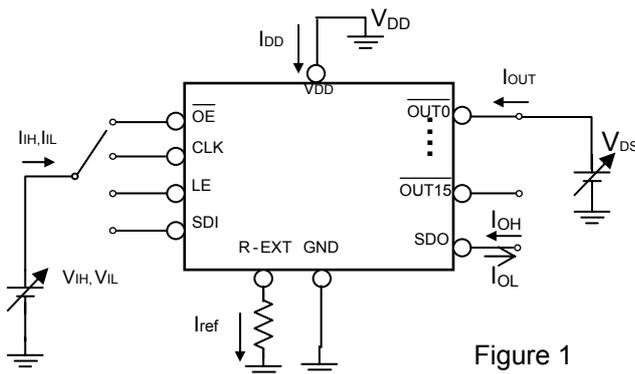


Figure 1

Switching Characteristics (V_{DD}=5.0V)

Characteristics		Symbol	Condition	Min.	Typ.	Max.	Unit
Propagation Delay Time ("L" to "H")	LE-SDO	t _{PLS}	V _{DD} =5.0V V _{DS} =1.0V V _{IH} =V _{DD} V _{IL} =GND R _{ext} =700Ω R _L =162Ω C _L =10pF I _{OUT} =20mA C ₁ =100nF C ₂ =22μF C _{SDO} =10pF	-	55	70	ns
	CLK-SDO	t _{pLH1}		-	25	30	ns
	LE- $\overline{\text{OUT0}}$	t _{pLH2}		-	20	-	ns
	$\overline{\text{OE}} - \overline{\text{OUT0}}$	t _{pLH3}		-	20	-	ns
Propagation Delay Time ("H" to "L")	LE-SDO	t _{PLS}		-	55	70	ns
	CLK-SDO	t _{pHL1}		-	25	30	ns
	LE- $\overline{\text{OUT0}}$	t _{pHL2}		-	28	-	ns
	$\overline{\text{OE}} - \overline{\text{OUT0}}$	t _{pHL3}		-	28	-	ns
Staggered Delay of Output	$\overline{\text{OUTn}} - \overline{\text{OUTn+1}}$	t _{stag}		-	2	-	ns
Pulse Width	CLK	t _{w(CLK)}		15	-	-	ns
	LE	t _{w(L)}		15	-	-	ns
Data Clock Frequency		F _{CLK}		-	-	30	MHz
Hold Time for LE		t _{h(L)}		10	-	-	ns
Setup Time for LE		t _{su(L)}		10	-	-	ns
Hold Time for SDI		t _{h(D)}		5	-	-	ns
Setup Time for SDI		t _{su(D)}		3	-	-	ns
Maximum CLK Rise Time*		t _r		-	-	500	ns
Maximum CLK Fall Time*		t _f		-	-	500	ns
SDO Rise Time		t _{r,SDO}		-	10	-	ns
SDO Fall Time		t _{f,SDO}		-	10	-	ns
Output Rise Time of Output Ports		t _{or}	15	25	-	ns	
Output Fall Time of Output Ports		t _{of}	10	15	-	ns	
In-message error detection time		t _{ERR-I}	255	300	345	ns	
Compulsory error detection time**		t _{ERR-C}	425	500	575	ns	
$\overline{\text{OE}}$ with uniform output		t _{w(OE)}	35	40	-	ns	
$\overline{\text{OE}}$ with uniform output		t _{w(OE)}	35	40	-	ns	

* If t_r or t_f is large, it may be critical to achieve the timing required for data transfer between two cascaded drivers.

** Please refer to "Compulsory Error Detection" section. The compulsory error detection time of MBI5039 is t_{ERR-C}, but it takes extra time to enter or exit the detection mode.

Switching Characteristics (V_{DD}=3.3V)

Characteristics		Symbol	Condition	Min.	Typ.	Max.	Unit
Propagation Delay Time ("L" to "H")	LE-SDO	t _{pLS}	V _{DD} =3.3V V _{DS} =1.0V V _{IH} =V _{DD} V _{IL} =GND R _{ext} =700Ω R _L =162Ω C _L =10pF I _{OUT} =20mA C ₁ =100nF C ₂ =22μF C _{SDO} =10pF	-	85	100	ns
	CLK-SDO	t _{pLH1}		-	30	35	ns
	LE- $\overline{\text{OUT0}}$	t _{pLH2}		-	30	-	ns
	$\overline{\text{OE}}$ - $\overline{\text{OUT0}}$	t _{pLH3}		-	30	-	ns
Propagation Delay Time ("H" to "L")	LE-SDO	t _{pLS}		-	85	100	ns
	CLK-SDO	t _{pHL1}		-	30	35	ns
	LE- $\overline{\text{OUT0}}$	t _{pHL2}		-	40	-	ns
	$\overline{\text{OE}}$ - $\overline{\text{OUT0}}$	t _{pHL3}		-	40	-	ns
Staggered Delay of Output	$\overline{\text{OUTn}} - \overline{\text{OUTn+1}}$	t _{stag}		-	2	-	ns
Pulse Width	CLK	t _{w(CLK)}		20	-	-	ns
	LE	t _{w(L)}		15	-	-	ns
Data Clock Frequency		F _{CLK}		-	-	25	MHz
Hold Time for LE		t _{h(L)}		10	-	-	ns
Setup Time for LE		t _{su(L)}		10	-	-	ns
Hold Time for SDI		t _{h(D)}		5	-	-	ns
Setup Time for SDI		t _{su(D)}		3	-	-	ns
Maximum CLK Rise Time*		t _r		-	-	500	ns
Maximum CLK Fall Time*		t _f		-	-	500	ns
SDO Rise Time		t _{r,SDO}		-	10	-	ns
SDO Fall Time		t _{f,SDO}		-	10	-	ns
Output Rise Time of Output Ports		t _{or}	20	30	-	ns	
Output Fall Time of Output Ports		t _{of}	30	40	-	ns	
In-message error detection time		t _{ERR-I}	255	300	345	ns	
Compulsory error detection time**		t _{ERR-C}	425	500	575	ns	
$\overline{\text{OE}}$ with uniform output		t _{w(OE)}	50	70	-	ns	
$\overline{\text{OE}}$ with uniform output		t _{w(OE)}					
			R _{ext} =230Ω I _{OUT} =60mA	-	300	-	ns

*If t_r or t_f is large, it may be critical to achieve the timing required for data transfer between two cascaded drivers.

** Please refer to "Compulsory Error Detection" section. The compulsory error detection time of MBI5039 is t_{ERR-C}, but it takes extra time to enter or exit the detection mode.

Test Circuit for Switching Characteristics

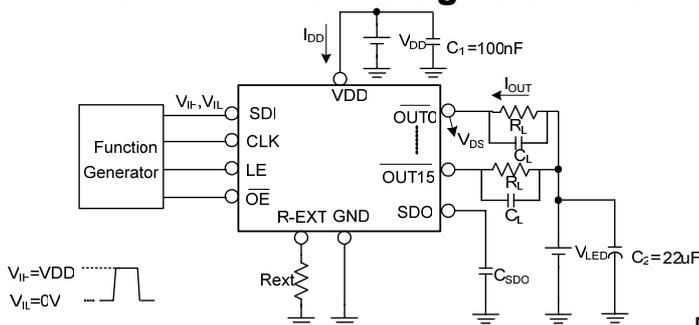
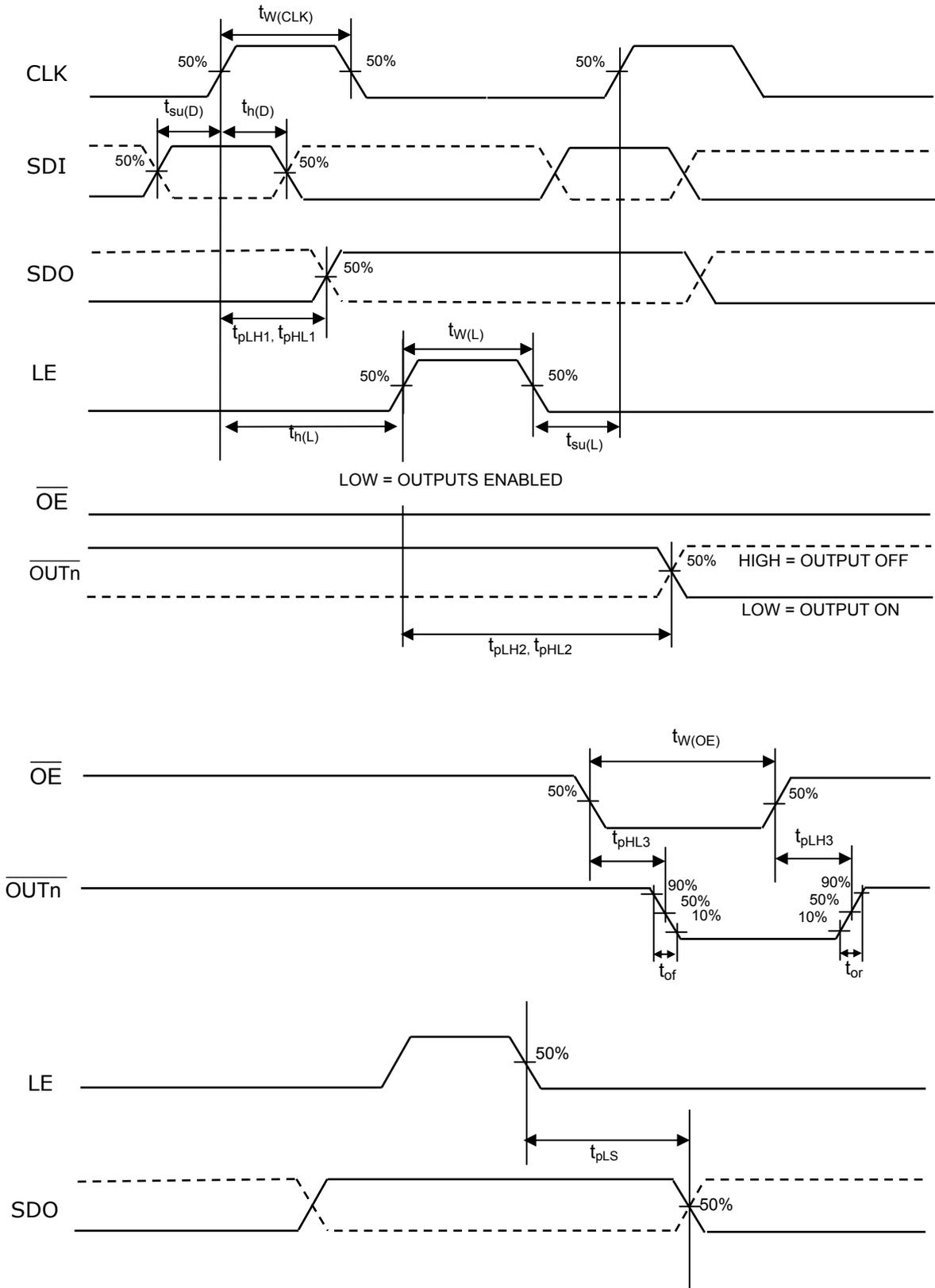
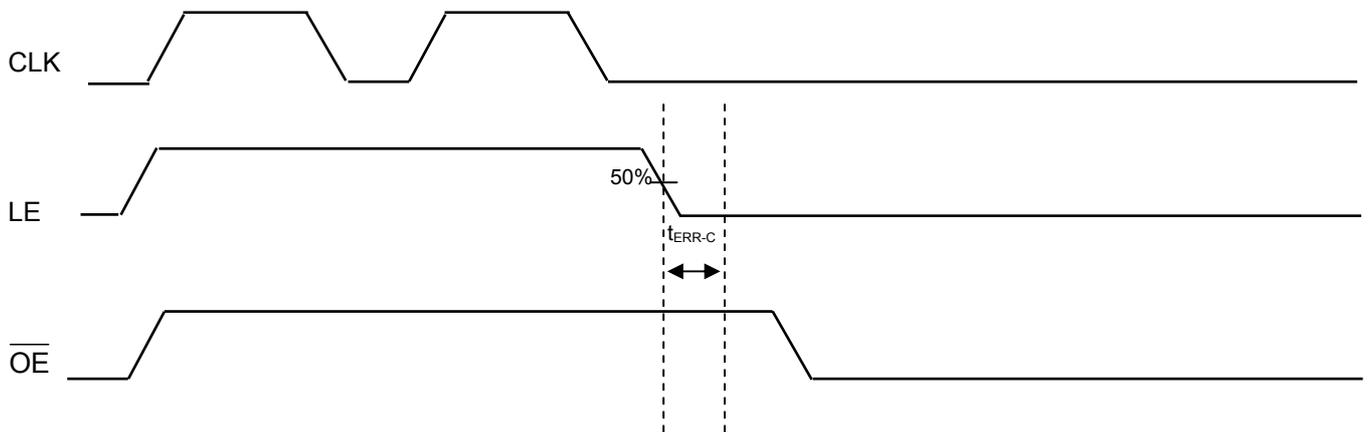
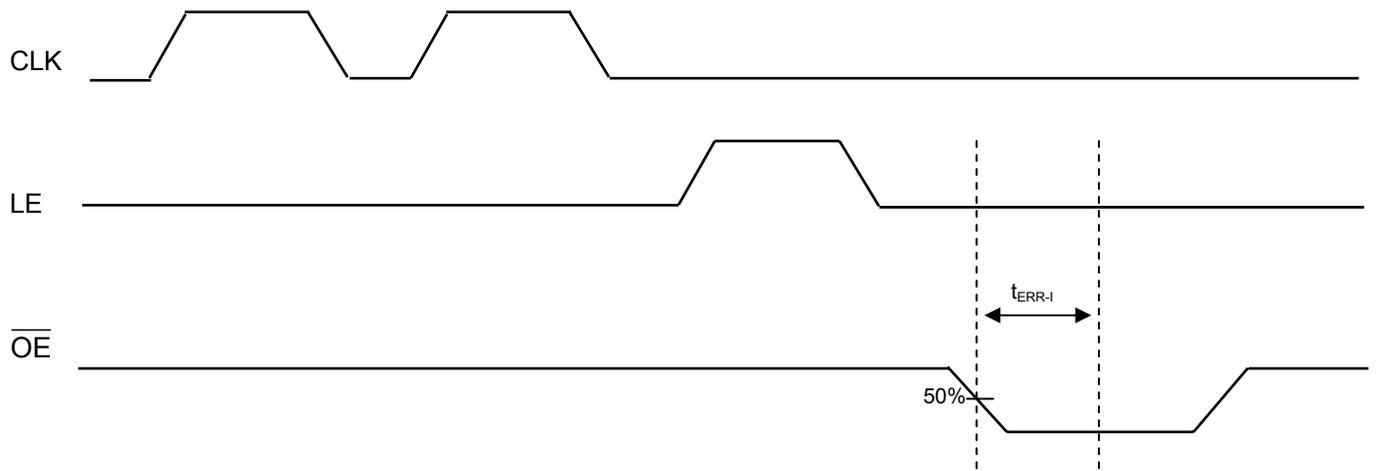


Figure 2

Timing Waveform

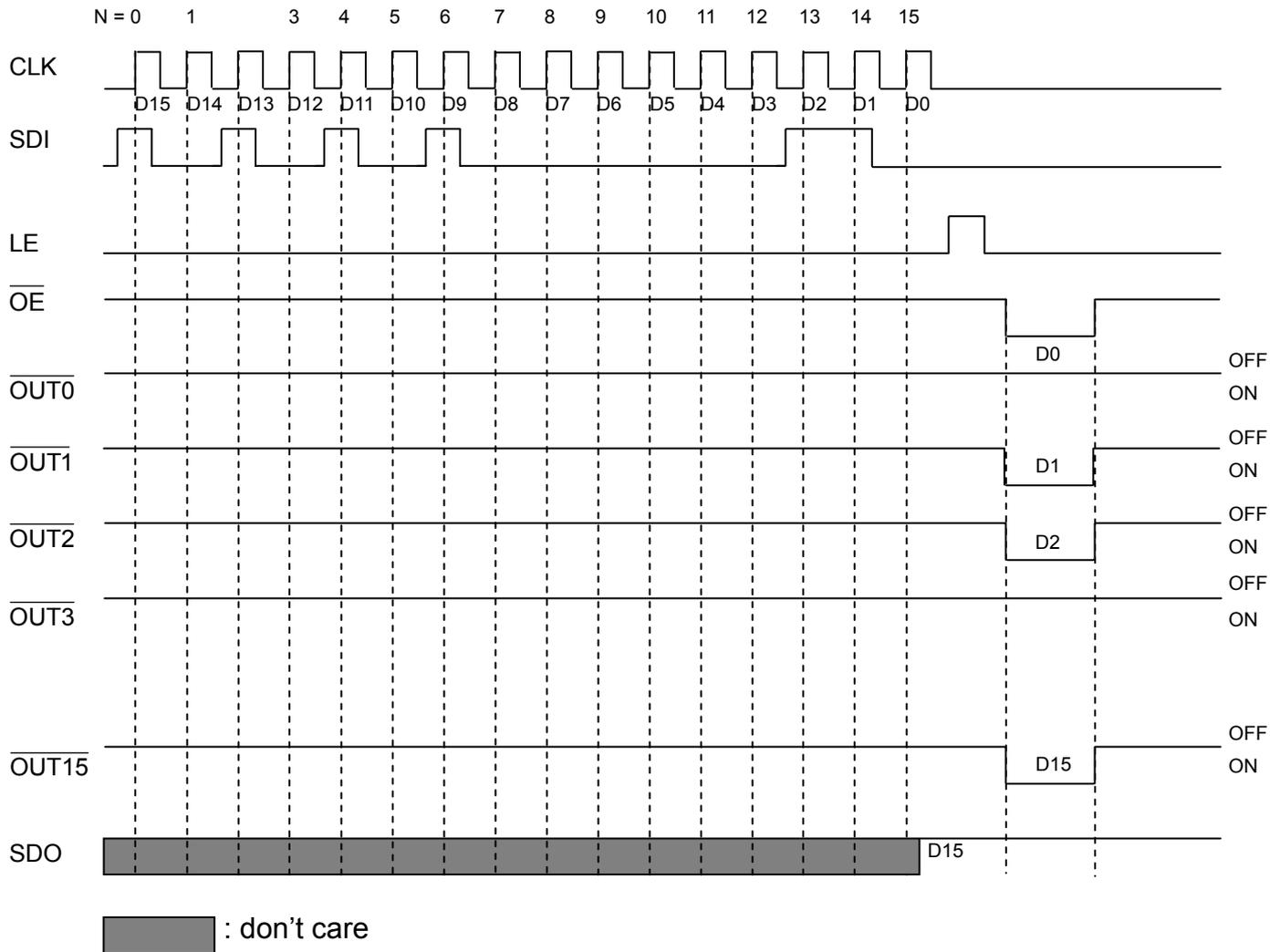




Control the Output Ports

The data is shifted from the SDI to the 16-bits shift registers. When both the LE is asserted and no CLK toggles when the LE is high, the data in the shift register is latched to the output latch. This is so-called “series-in parallel out” mechanism.

When the \overline{OE} is low and the data in the output latch is “1”, the output channel is turned on and the current sinks into the output port. If LEDs are connected to the output port with adequate power source, the LEDs will be lit up with the pre-set current.



Control Command

	Signals Combination*	Description
Command Name	Number of CLK Rising Edge when LE is asserted	The Action after a Falling Edge of LE
Latch data (In-message error detection)	0	Latch the serial data to the output latch. Perform the in-message error detection if it is enabled in the setting of configuration register. In-message error detection includes open-circuit detection and short-circuit detection.
Compulsory open-circuit detection	1	Issue "open-circuit error detection" once. The data latching will not occur.
Compulsory short-circuit detection	2	Issue "short-circuit error detection" once. The data latching will not occur.
Compulsory thermal detection	3	Issue "IC thermal detection" once. The data latching will not occur.
Write configuration	4	Serial data are transferred to the "configuration register"

*See section of "Principle of Operation" for detail timing diagram

Data output from SDO

Command	SDO after a falling edge of LE
Latch data, in-message error detection is enabled	Error code of in-message error detection; it needs wait t_{pLS} after the falling edge of LE.
Latch data, in-message error detection is disabled	Serial data input ; the data had latched into output buffer
Compulsory open-circuit detection	Error code of Compulsory open-circuit detection. it needs wait t_{ERR-C}^* , after the falling edge of LE.
Compulsory short-circuit detection	Error code of Compulsory short-circuit detection t needs wait t_{ERR-C}^* , after the falling edge of LE.
Compulsory thermal detection	Thermal report; it needs wait t_{pLS} after the falling edge of LE.
Write configuration	Serial data input ; the data had latched into configuration register

*See section of "Principle of Operation" for detail timing diagram

Error code

	Error flag for corresponding bit in the shift register
Open or short error is detected in the channel	0
Neither open nor short error is detected in the channel (Or detection is suppressed)	1

If the condition of valid error detection is not matched, the detection is suppressed. Please refer to section of "Principle of Operation" for the condition of valid error detection..

Principle of Operation

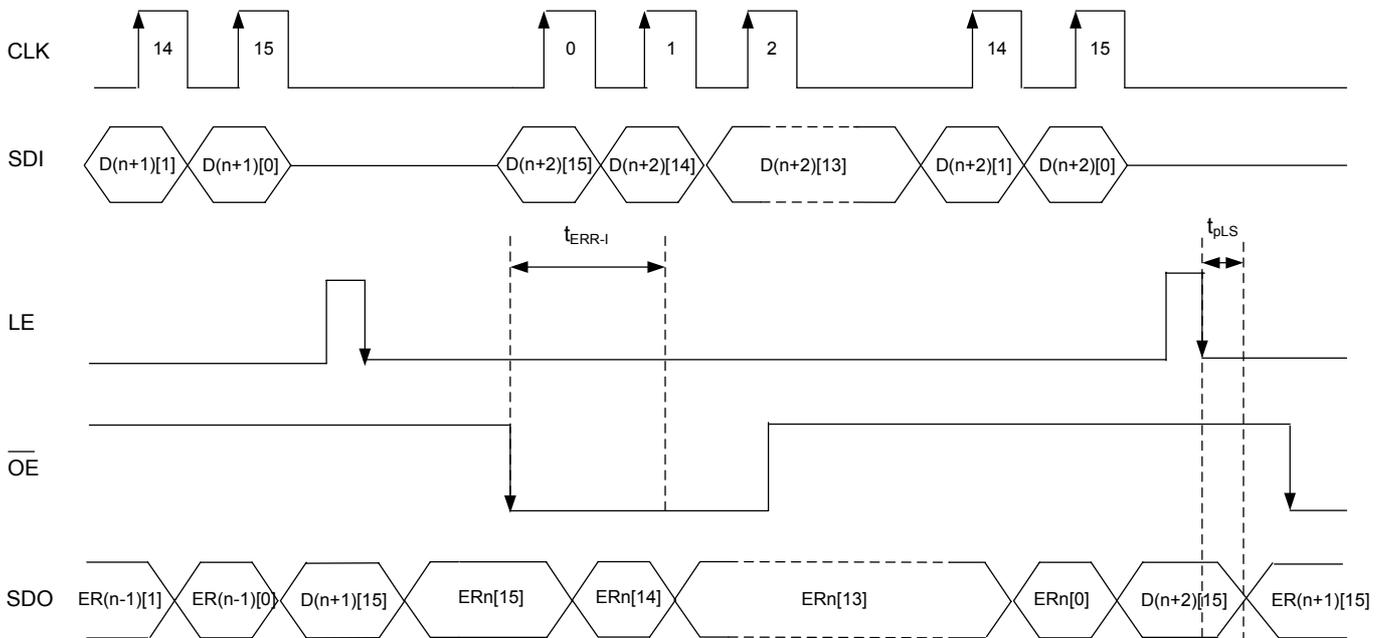
In-Message Error Detection

If the in-message error detection is enabled in the configuration register, the in-message error detection will perform on-the-fly open- and short-circuit detection as data-in and error-out sequentially. The errors are merged and coded with zeros.

The output is detected only when the output data is "1" and \overline{OE} pulse width is larger than t_{ERR-I} , preventing from false error report. This is because the detection result is correct only if the LED is lit up. The error code showed as "0" helps the system identify the errors precisely without comparing data "0" or data "1".

If the in-message error detection can be disabled in the configuration register, the error detection will not be performed and the SDO shifts out the data from the shift register which the SDI is shifted into.

With the in-message error detection, the controller just checked if the data from SDO is "0" to identify the error location without considering the input data, \overline{OE} status and issuing any extra command.



1. Condition of valid error detection: (1) Data = "1" (2) \overline{OE} (low) > t_{ERR-I}

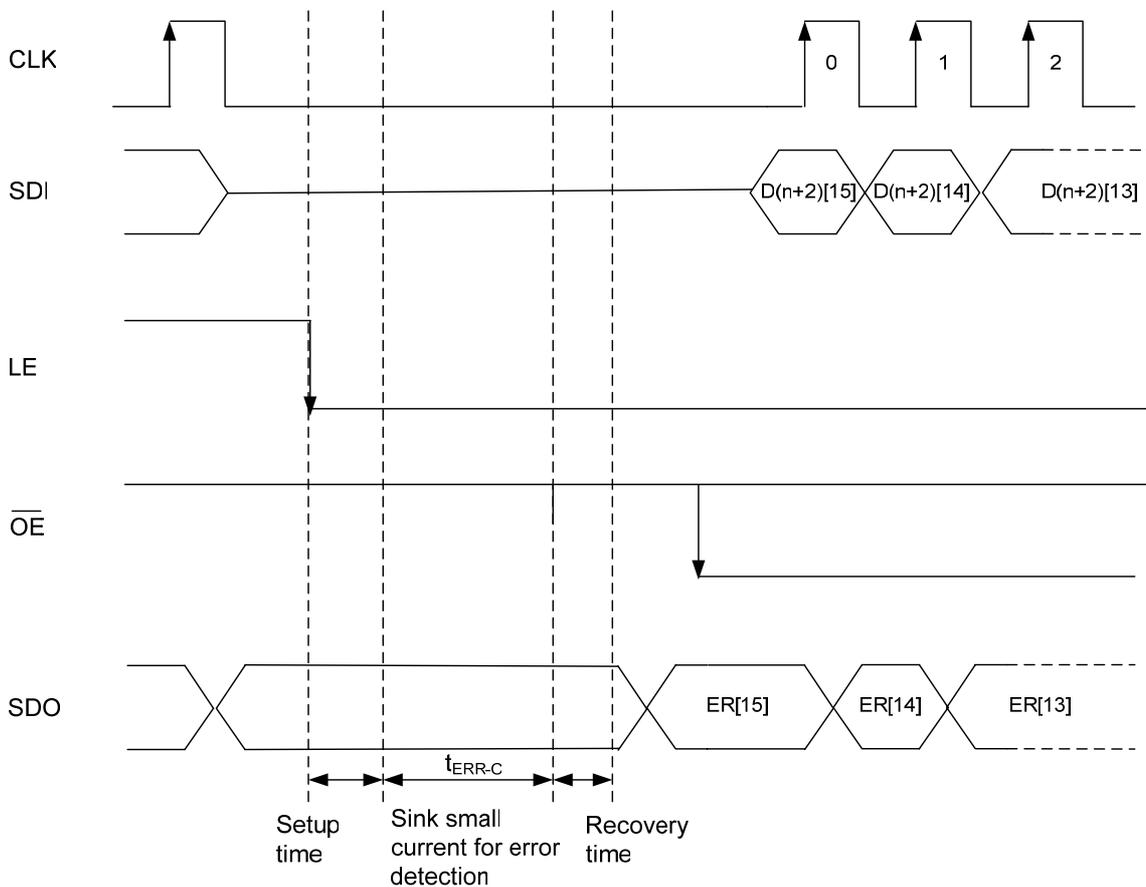
Note: If the above condition is not matched, the error detection is suppressed and error codes remain "1"

2. After the falling edge of the LE, the time required for the driver to deliver the error report to the shift register is t_{pLS} .

Compulsory Error Detection

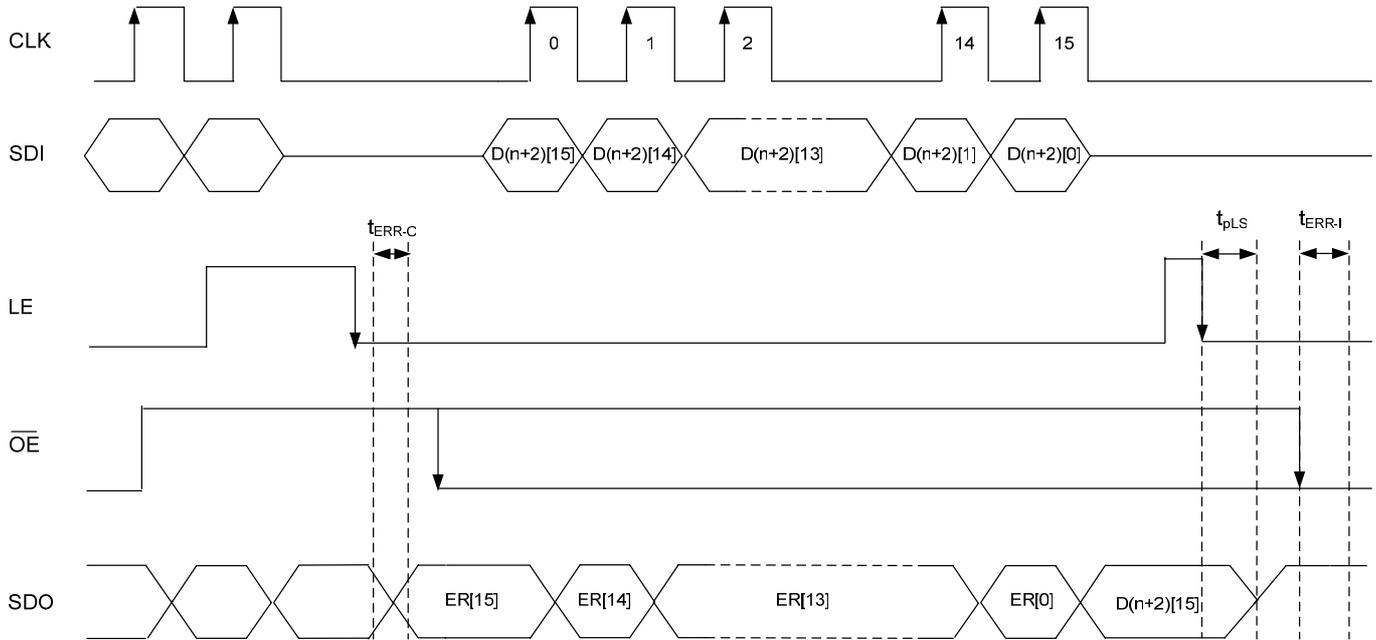
Compulsory error detection is “silent error detection”, also named as “dark” or “blind” error detection. No matter the data is 1 or 0, the output will be turned on with 0.1mA in t_{ERR-C} in the compulsory error detection mode. The turn-on time and turn-on current are short and small, so that the human eye will not perceive detection and the quality of the video and image are not influenced. According to the issued “control commands”, the compulsory “silent” error detection will run open-circuit or short-circuit detection separately. If an LED is open- or short-circuit, the error code will be “0” and shifted out through SDO once only.

Beside the t_{ERR-C} , MBI5039 also needs time to set up the detection condition and to recover to the normal operation mode, such as adjusting the output current. It takes about 50~100ns to enter or exit the detection mode. It is recommended to reserve 700ns for safe operation.



Compulsory Open-Circuit Detection

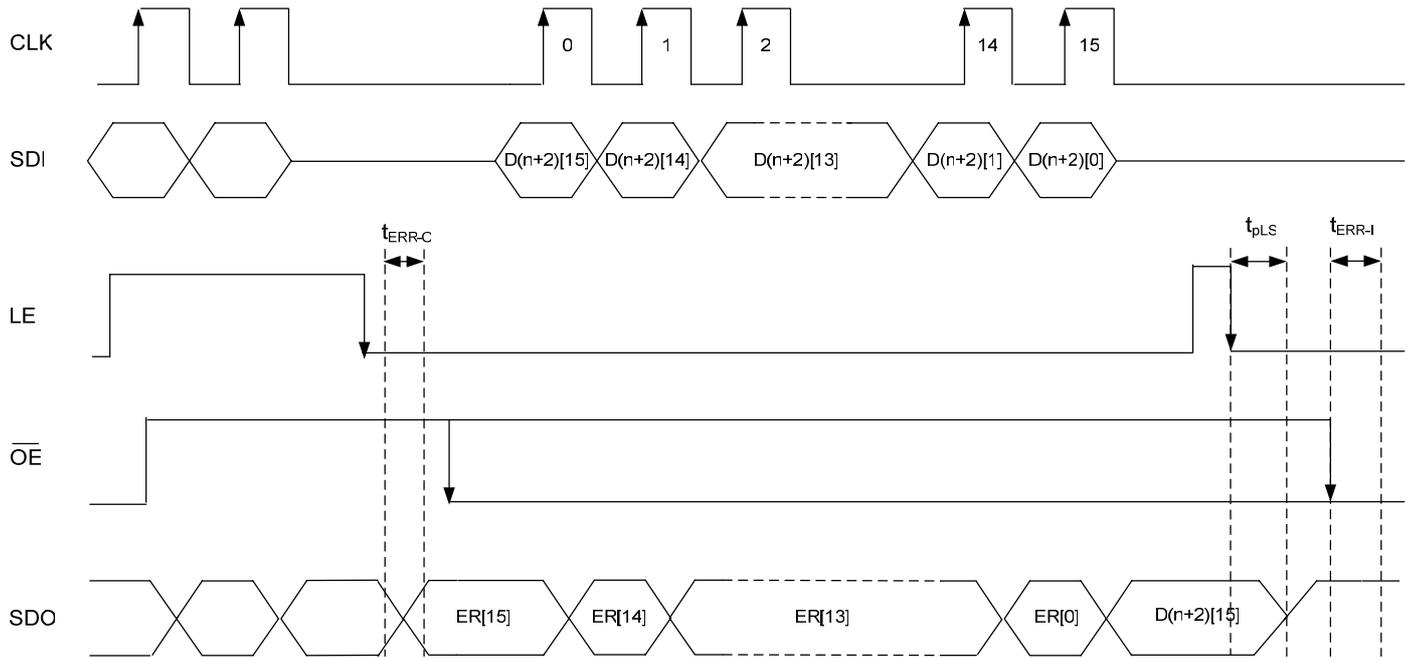
The principle of MBI5039 LED open-circuit detection is based on the fact that the LED loading status is judged by comparing the effective voltage value (V_{DS}) of each output port with the target voltage ($V_{OD,TH} = 0.3V$). Thus, after the command of “compulsory open-circuit detection”, the output ports of MBI5039 will be turned on with 0.1mA in t_{ERR-C} . Then, the error status saved in the built-in register is shifted out through SDO pin bit by bit while receiving the new data simultaneously.



1. Conditions required to activate the open-circuit detection: (1) falling edge of LE and (2) $\overline{OE} = \text{High}$
 2. Condition of valid error detection: (1) $\overline{OE} = \text{high}$ during t_{ERR-C}
- Note: If the above condition is not matched, the error detection is suppressed and error codes remain “1”.
3. At the falling edge of LE, all output channels are turned on within 0.1mA.
 4. The error detection starts and then loads error result to shift register in t_{ERR-C} duration..
 5. If the \overline{OE} is asserted during t_{ERR-C} , the error detection process will be aborted.
 6. If CLK is toggled before t_{ERR-C} , the shifted-in data in the shift register will be destroyed at t_{ERR-C} .

Compulsory Short-Circuit Detection

When LED is damaged, a short-circuit error may occur. To effectively detect the short-circuit error, the principle of MBI5039 LED short-circuit detection is based on the fact that the LED voltage drop is judged by comparing the effective voltage value (V_{DS}) of each output port with the target voltage ($V_{SD.TH} = 0.45 \times V_{DD}$, default). Please refer to the “Setting the Threshold Voltage for Short-Circuit Detection” for details. Thus, after the command of “compulsory short-circuit detection”, the output ports of MBI5039 will be turned on with 0.1mA in t_{ERR-C} . Then, the error status saved in the built-in register is shifted out through SDO pin bit by bit while receiving the new data simultaneously.



1. Conditions required to activate the short-circuit detection: (1) falling edge of LE and (2) $\overline{OE} = \text{High}$
2. Condition of valid error detection: (1) $\overline{OE} = \text{high}$ during t_{ERR-C}

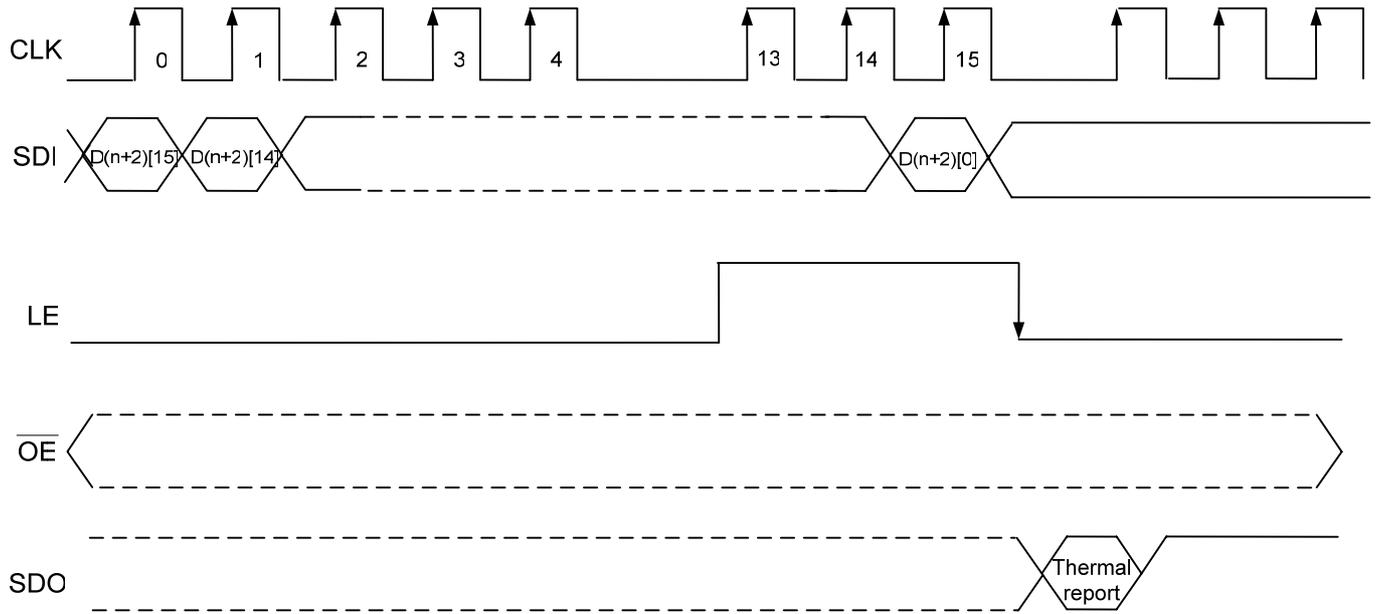
Note: If the above condition is not matched, the error detection is suppressed and error codes remain “1”.

3. At the falling edge of LE, all output channels are turned on within 0.1mA.
4. The error detection starts and then loads error result to shift register in t_{ERR-C} duration
5. If the \overline{OE} is asserted during t_{ERR-C} , the error detection process will be aborted.
6. If CLK is toggled before t_{ERR-C} , the shifted-in data in the shift register will be destroyed at t_{ERR-C} .

Compulsory Thermal Detection

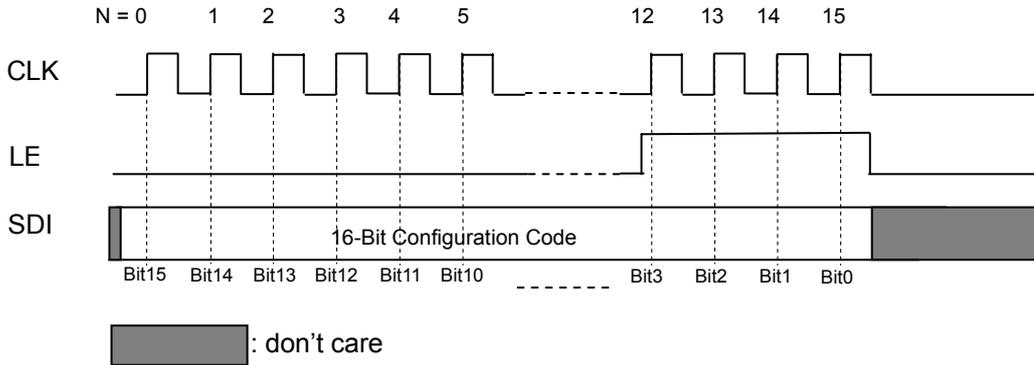
The thermal error flag indicates an overheating condition. When IC's junction temperature is over 150°C (typ.), the bit 15 of the shift register is set to "0".

	Thermal code
The junction temperature of MBI5039 $\geq T_{TF}$	0
The junction temperature of MBI5039 $< T_{TF}$	1



At the falling edge of LE, if the driver is overheated, the code "7FFF(HEX)" is delivered to SDO; otherwise, the code "FFFF(HEX)" is latched to shift register. The data "D(n+2) []" will not be latched into the output buffer.

Writing Configuration Code



After entering the writing configuration mode, the system controller sends a 16-bit configuration register to 16-bit shift register through the SDI pin. Then the falling edge of LE will transfer the contents in the shift register to a 16-bit configuration register rather than the 16-bit output latch.

Definition of Configuration Register

MSB														LSB	
F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0

e.g. Default Value

F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0
0	1	1	0	Reserved bits:000000						6'b101011					

Bit	Definition	Value	Function
F~E	Voltage thresholds for short-circuit detection($V_{SD,TH}$)	00	$0.33 \times V_{DD} \pm 0.1V$
		01 (Default)	$0.45 \times V_{DD} \pm 0.1V$
		10	$0.58 \times V_{DD} \pm 0.1V$
		11*	$0.73 \times V_{DD} \pm 0.1V$
D~C	In-message error detection	00	Disable in message error detection; SDO shifts out input data from SDI.
		01	Enable LE to trigger in-message error detection; SDO shift out error code as "Error Code" section.
		10 (Default)	Enable \overline{OE} to trigger in-message error detection; SDO shift out error code as "Error Code" section.
		11	Enable \overline{OE} or LE to trigger in-message error detection; SDO shift out error code as "Error Code" section.
B~6	Reserved bits	000000	Reserved
5~0	Current gain	000000 ~ 111111	6'b101011 (Default): allow 64-step programmable current gain from 12.5 % to 200%

*Configuration register=11: when both $V_{DD}=5V$ and in the in-message error detection mode, the $V_{SD,TH}=0.73 \times V_{DD}+0.4V$. In other conditions, $V_{DS,TH}$ is $0.73 \times V_{DD}$.

Setting the Threshold Voltage for Short-Circuit Detection

The default threshold voltage for short-circuit detection ($V_{SD,TH}$) equals to $0.45 \times V_{DD}$. If the detected voltage is larger than $V_{SD,TH}$, the MBI5039 identifies the LED as short-circuit.

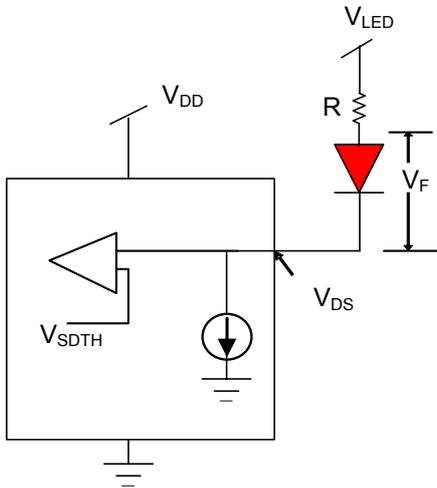


Figure 3

MBI5039 provides settable $V_{SD,TH}$ for different LED configuration. For example, if each output port of MBI5039 drives one red LED, the $V_{SD,TH}$ shall be set larger. If each output port of MBI5039 drives one blue LED, the $V_{SD,TH}$ shall be set smaller. In addition, the system shall consider accumulated V_F of the LED to set the suitable $V_{SD,TH}$. The system needs to set the suitable $V_{SD,TH}$, V_{LED} , and V_{DD} for different color LEDs.

Consider:

Normal condition : $V_{DS} = V_{LED} - I \times R - V_{F(normal)}$

Short-circuit condition: $V_{DS} = V_{LED} - I \times R - V_{F(short)}$; $V_{F(short)} < V_{F(normal)}$

Select $V_{SD,TH}$ to meet:

$V_{LED} - I \times R - V_{F(normal)} < V_{SD,TH} < V_{LED} - I \times R - V_{F(short)}$

V_F and I are the values with detection current: 0.1mA (Compulsory error detection) or normal current (in-message error detection)

The variation of each value should be considered.

For example,

a green LED,

$V_{F(normal)} = 3.5 \sim 3.7V$,

$V_{F(short)} < 1.5V$,

and R is not used ($R=0$),

$V_{LED} = 4.7 \sim 5.3V$,

Therefore, in the normal condition, $V_{DS} = 1 \sim 1.8V$,

and in the short-circuit condition = $V_{DS} > 3.2V$

If $V_{DD} = 5V$, $V_{DS,TH} = 0.45 \times V_{DD} = 2.25V$ is a good choice;

if $V_{DD} = 3.3V$, $V_{DS,TH} = 0.73 \times V_{DD} = 2.41V$ is a good choice.

In some cases, the V_{DD} , V_{LED} , and R may need to be optimized for different color LEDs. With the adjustable $V_{SD,TH}$, the selections of these values can be more flexible and reduce the necessity of using dual voltage for operation and error detection.

For the compulsory error detection, the $V_{F(normal)}$, $V_{F(short)}$ shall consider the LED current to be 0.1mA. These two values will be smaller than those in the normal current.

Constant Current

In LED display applications, MBI5039 provides nearly no current variations from channel to channel and from IC to IC. This can be achieved by:

- 1) While $I_{OUT} \leq 90\text{mA}$, $V_{DD}=5\text{V}$, the maximum current skew between channels is less than $\pm 1.5\%$ (typical) and that between ICs is less than $\pm 3\%$ (typical).
- 2) In addition, the characteristics curve of output stage in the saturation region is flat and users can refer to the charts as shown below. Thus, the output current keeps constant regardless of the variations of LED forward voltages (V_F). The output current level in the saturation region is defined as output target current $I_{out,target}$.

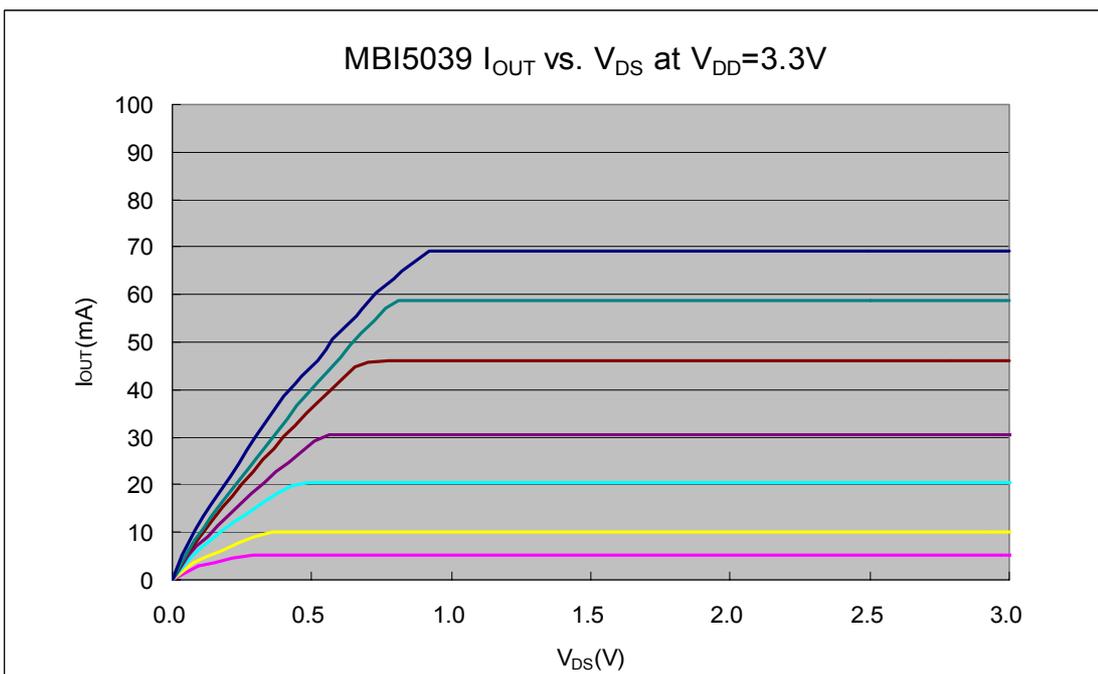
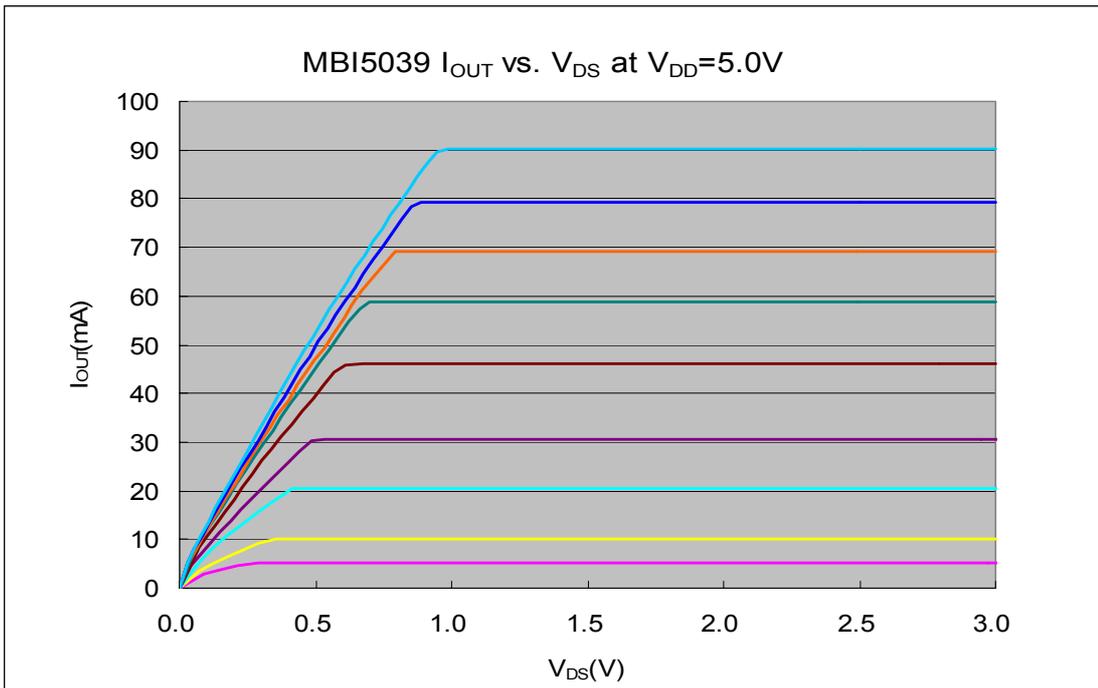


Figure 4

Setting Output Current

The output current (I_{OUT}) is set by an external resistor, R_{ext} . The default relationship between I_{OUT} and R_{ext} is shown in the following figure.

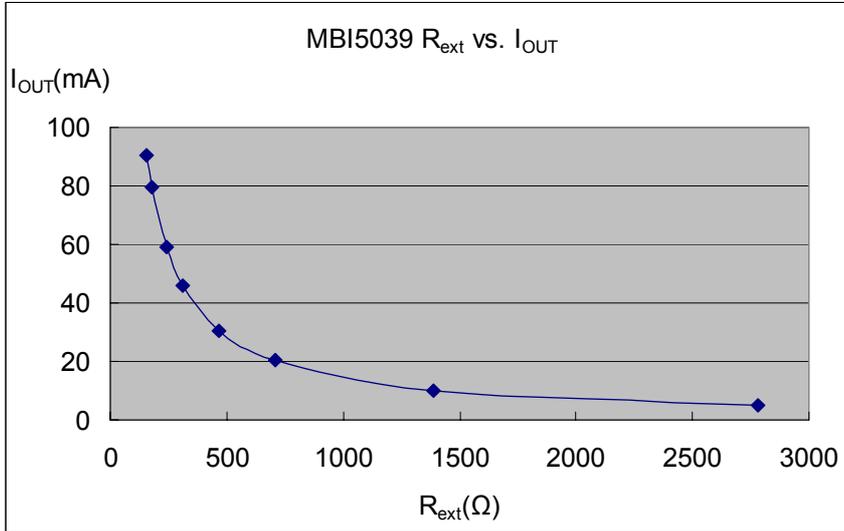


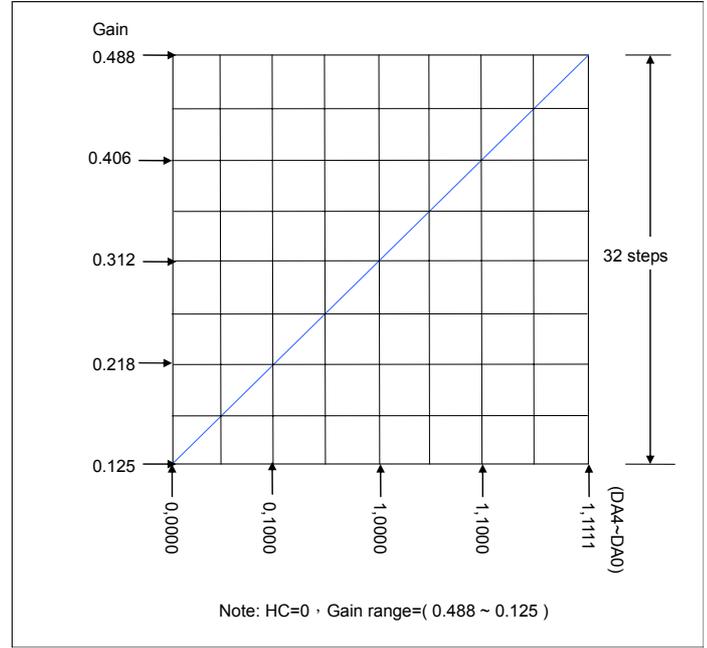
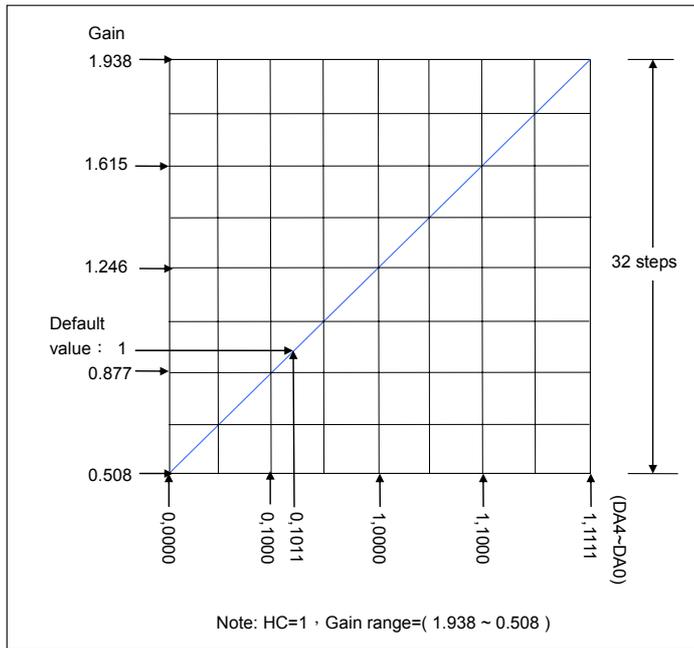
Figure 5

Also, the output current can be calculated from the equation:

$$V_{R-EXT} = 0.61\text{Volt} \times G; I_{OUT} = (V_{R-EXT} / R_{ext}) \times 23.0$$

Whereas R_{ext} is the resistance of the external resistor connected to R-EXT terminal and V_{R-EXT} is its voltage. G is the digital current gain, which is set by the bit 5 to bit 0 of the configuration register. The default value of G is 1. For your information, the output current is about 20.2mA when $R_{ext}=700\Omega$ and 62.3mA when $R_{ext}=230\Omega$ if G is set to default value 1. The formula and the setting for G are described in the next section.

Current Gain Adjustment



The 6 bits (bit 5~bit 0) of the configuration register set the gain of output current, i.e., G. As total 6-bit in number, i.e., ranged from 6'b000000 to 6'b111111, these bits allow the user to set the output current gain up to 64 levels. These bits can be further defined inside configuration register as follows:

F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0
-	-	-	-	-	-	-	-	-	-	HC	DA4	DA3	DA2	DA1	DA0

1. Bit 5 is HC bit. The setting is in low current band when HC=0, and in high current band when HC=1.
2. Bit 4 to bit 0 are DA4 ~ DA0.

The relationship between these bits and current gain G is:

$$HC=1, D=(65xG-33)/3$$

$$HC=0, D=(256xG-32)/3$$

and D in the above decimal numeration can be converted to its equivalent in binary form by the following equation:

$$D= DA4x2^4+DA3x2^3+DA2x2^2+DA1x2^1+DA0x2^0$$

In other words, these bits can be looked as a floating number with 1-bit exponent HC and 5-bit mantissa DA4~DA0.

For example,

$$HC=1, G=1.246, D=(65x1.246-33)/3=16$$

the D in binary form would be:

$$D=16=1x2^4+0x2^3+0x2^2+0x2^1+0x2^0$$

The 6 bits (bit 5~bit 0) of the configuration register are set to 6'b110000.

Staggered Delay of Output

MBI5039 has a built-in delay circuit to perform delay mechanism. Among output ports exist a graduated 2ns delay time among \overline{OUTn} and $\overline{OUTn+1}$, by which the output ports will be turned on at a different time so that the instant current from the power line will be lowered.

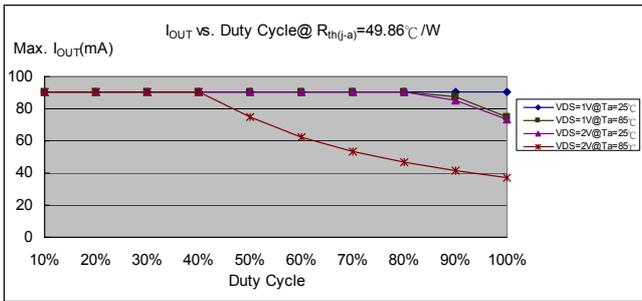
Package Power Dissipation (P_D)

The allowable maximum package heat dissipation is determined as $P_D(max)=(T_j-T_a)/R_{th(j-a)}$. When 16 output channels are turned on simultaneously, the actual package power dissipation is

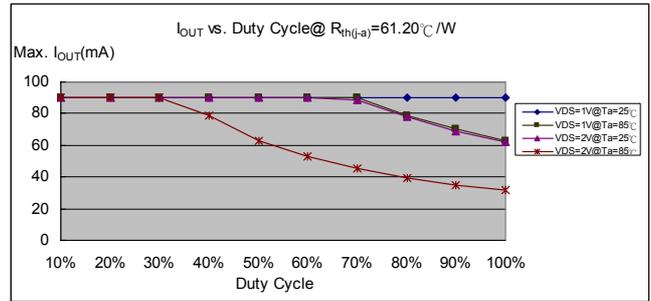
$P_D(act)=(I_{DD} \times V_{DD})+(I_{OUT} \times Duty \times V_{DS} \times 16)$. Therefore, to keep $P_D(act) \leq P_D(max)$, the allowable maximum output current as a function of duty cycle is:

$$I_{OUT} = \{[(T_j - T_a) / R_{th(j-a)}] - (I_{DD} \times V_{DD})\} / V_{DS} / Duty / 16,$$

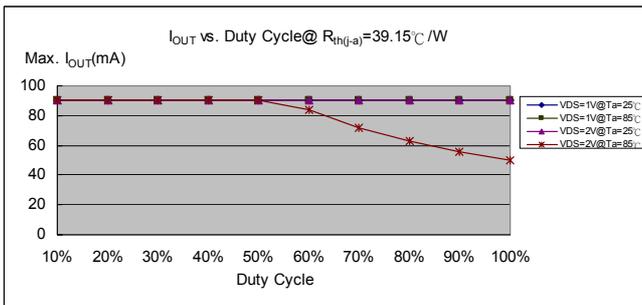
where $T_j = 150^\circ C$.



MBI5039GF



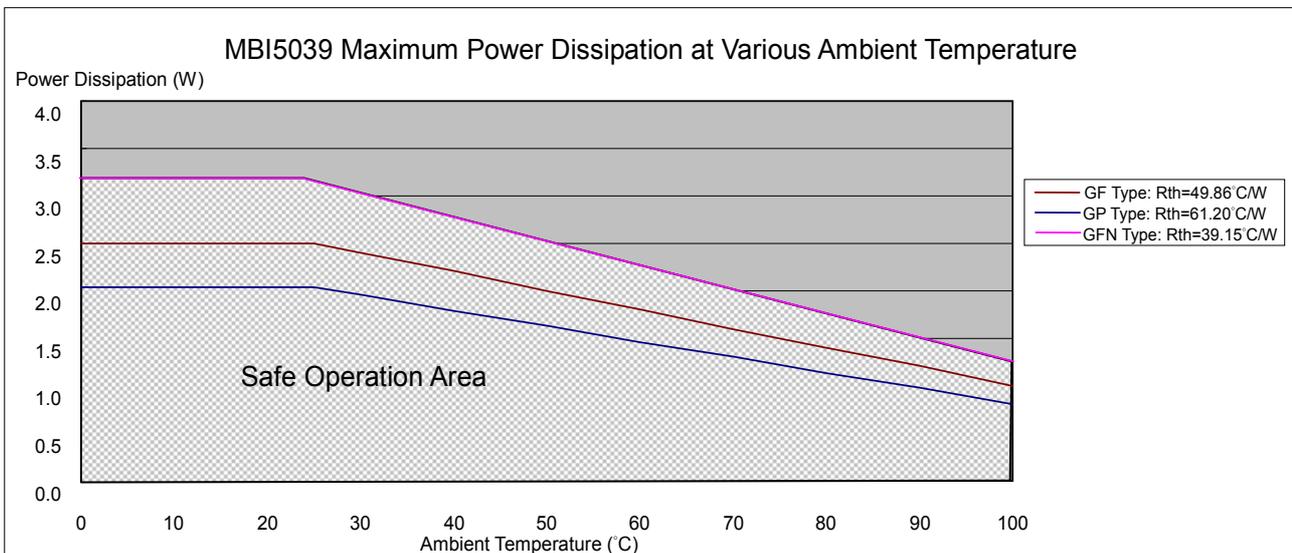
MBI5039GP



MBI5039GFN

Device Type	R _{th(j-a)} (°C/W)
GF	49.86
GP	61.20
GFN	39.15

The maximum power dissipation, $P_D(max)=(T_j-T_a)/R_{th(j-a)}$, decreases as the ambient temperature increases.



Load Supply Voltage (V_{LED})

MBI5039 is designed to operate with V_{DS} ranging from 0.4V to 1.0V, considering the package power dissipating limits. V_{DS} may be higher enough to make $P_{D(act)} > P_{D(max)}$ when $V_{LED} = 5V$ and $V_{DS} = V_{LED} - V_F$, in which V_{LED} is the load supply voltage. In this case, it is recommended to use the lowest possible supply voltage or to set an external voltage reducer (V_{DROP}).

A voltage reducer lets $V_{DS} = (V_{LED} - V_F) - V_{DROP}$.

Resistors or zener diode can be used in the applications as shown in the following figures.

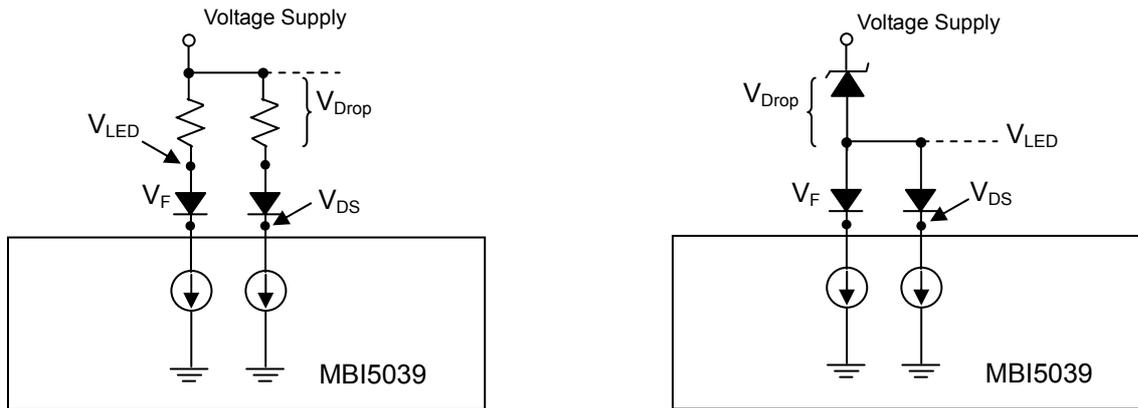
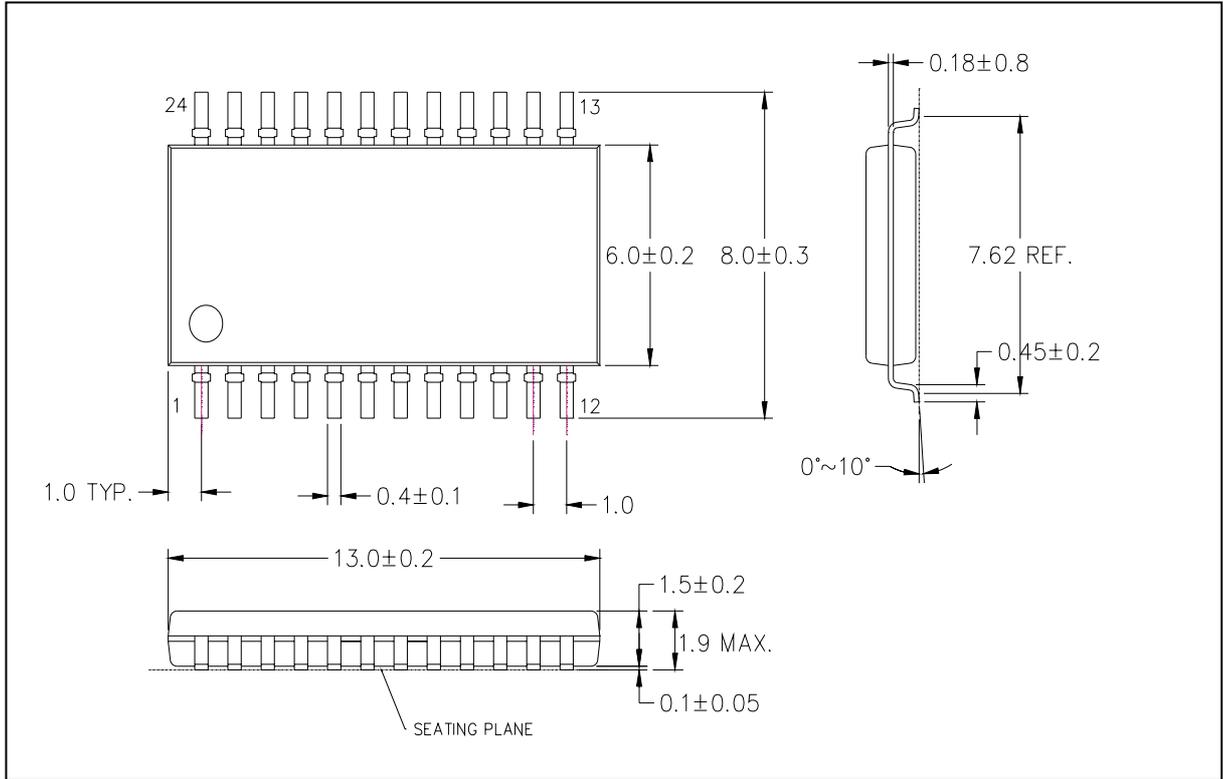


Figure 6

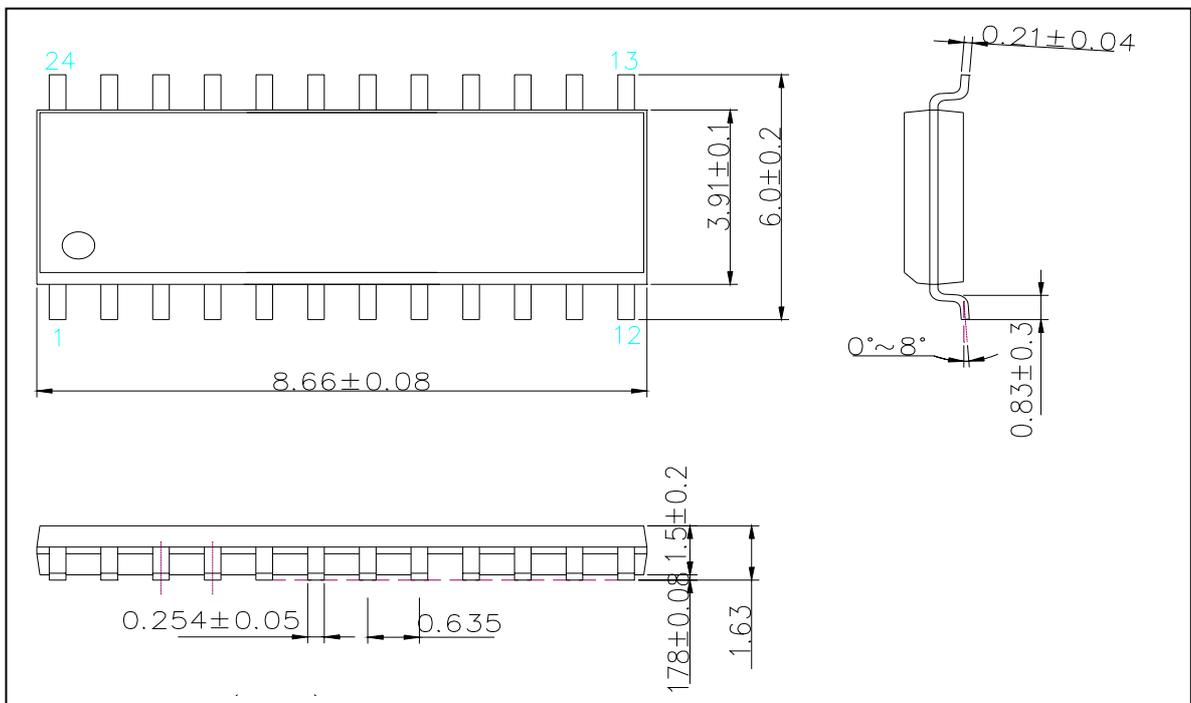
Switching Noise Reduction

LED driver ICs are frequently used in switch-mode applications which always behave with switching noise due to parasitic inductance on PCB. To eliminate switching noise, refer to “Application Note for 8-bit and 16-bit LED Drivers- Overshoot”.

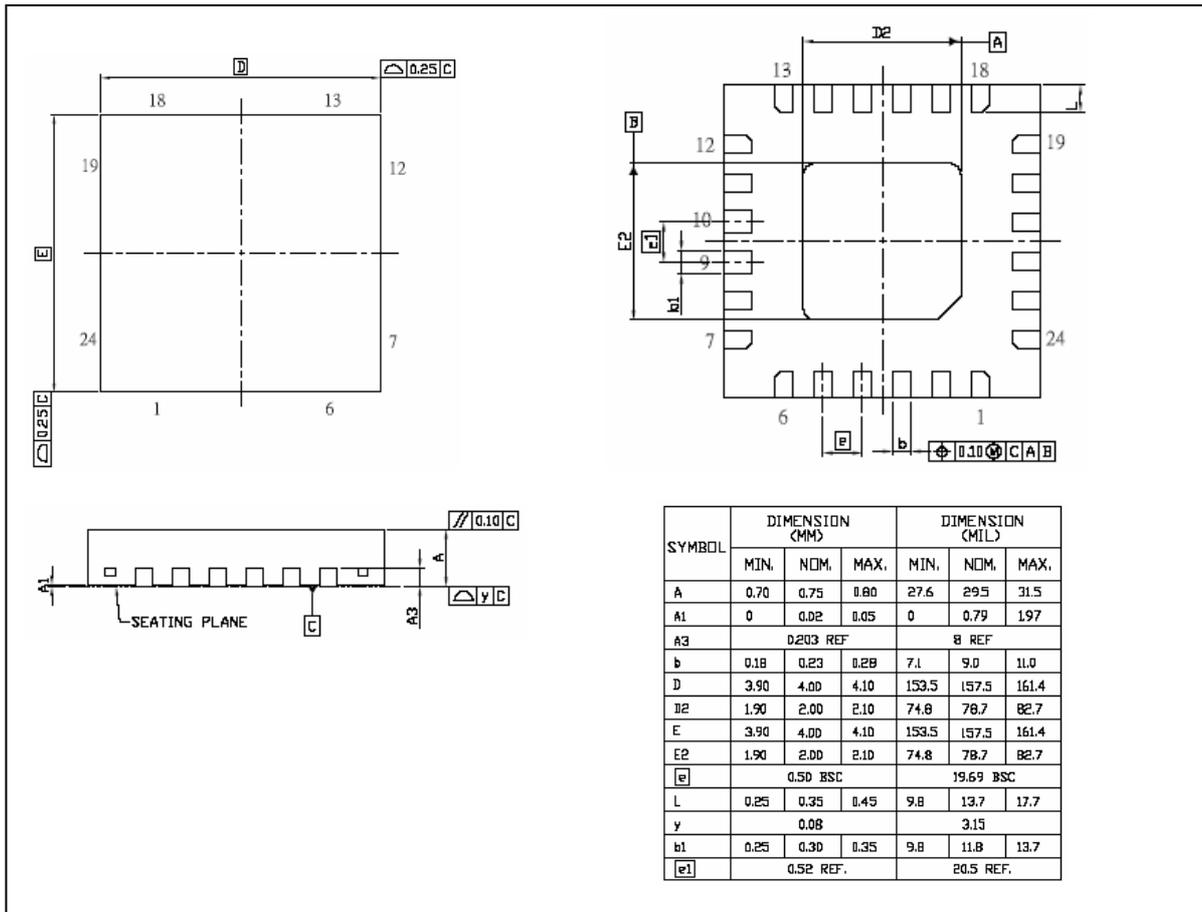
Package Outline



MBI5039GF Outline Drawing



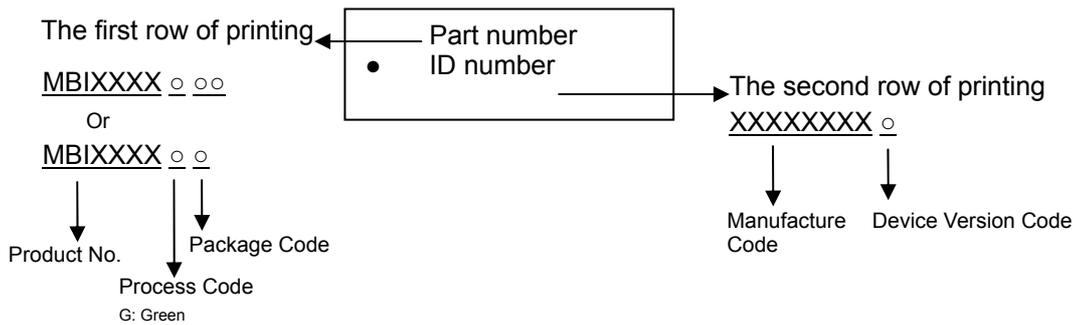
MBI5039GP Outline Drawing



MBI5039GFN Outline Drawing

Note: The unit for the outline drawing is mm.

Product Top-mark Information



Product Revision History

Datasheet version	Device version code
V1.00	A
V1.01	A

Product Ordering Information

Part Number	“Pb-free & Green” Package Type	Weight (g)
MBI5039GF	SOP24-300-1.00	0.28
MBI5039GP	SSOP24-150-0.64	0.11
MBI5039GFN	QFN24-4*4- 0.5	0.0379

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