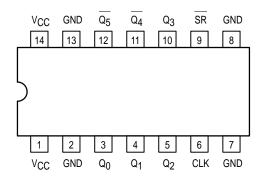
Low Skew CMOS Clock Driver With Reset

The MC88914 is a high–speed, low power, hex divide–by–two D–type flip–flop with matched propagation delays, an internal power–on–reset, and external synchronous reset. With TTL compatible buffered clock and external reset inputs that are common to all flip–flops, the MC88914 is ideal for use in high–frequency systems as a clock driver, providing multiple outputs that are synchronous.

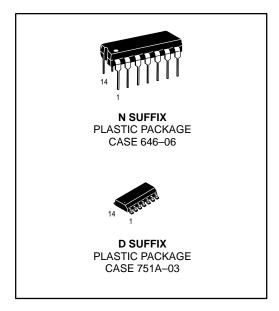
- Power-on-Reset and External Synchronous Reset
- TTL Compatible Positive Edge-Triggered Clock
- Matched Outputs for Synchronous Applications
- Outputs Source/Sink 24mA
- Part-to-Part Skew of Less Than 3.0ns
- Guaranteed Rise and Fall Times for a Given Capacitive Load

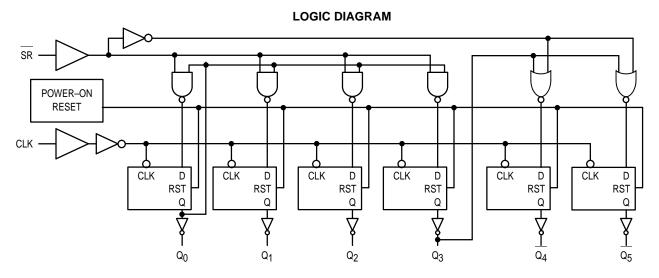
Pinout: 14-Lead Plastic (Top View)



MC88914

LOW SKEW CMOS CLOCK DRIVER WITH RESET





NOTE: This diagram is provided only for understanding of logic operation and should not be used to estimate propagation delays

REV 4

MOTOROLA

DC CHARACTERISTICS (unless otherwise specified)

Symbol	Parameter		Unit	Condition
ICC	Maximum Quiescent Supply Current	80	μΑ	V _{IN} = V _{CC} or GND V _{CC} = 5.5V, T _A = Worst Case
ICC	Maximum Quiescent Supply Current	8.0	μΑ	$V_{IN} = V_{CC}$ or GND $V_{CC} = 5.5V$, $T_A = 25^{\circ}C$
ICCT	Maximum Additional ICC/Input	1.5	mA	$V_{IN} = V_{CC} - 2.1V$ $V_{CC} = 5.5V$, $T_A = Worst Case$

DC CHARACTERISTICS

			T _A = +25°C		T _A = –40 to +85°C		
Symbol	Parameter	vcc	Тур	Gua	Guaranteed Max		Conditions
VIH	Minimum High Level Input Voltage	4.5 5.5	1.5 1.5	2.0 2.0	2.0 2.0	V	V _{OUT} = 0.1V or V _{CC} – 0.1V
V _{IL}	Maximum Low Level Input Voltage	4.5 5.5	1.5 1.5	0.8 0.8	0.8 0.8	V	V _{OUT} = 0.1V or V _{CC} – 0.1V
VOH	Minimum High Level	4.5 5.5	4.49 5.49	4.4 5.4	4.4 5.4	V	I _{OUT} = -50μA
		4.5 5.5		3.86 4.86	3.76 4.76	V	* V _{IN} = V _{IL} or V _{IH} I _{OH} = -24mA -24mA
VOL	Maximum Low Level Output Voltage	4.5 5.5	0.001 0.001	0.1 0.1	0.1 0.1	V	Ι _{ΟΟΤ} = 50μΑ
		4.5 5.5		0.36 0.36	0.44 0.44	V	*V _{IN} = V _{IL} or V _{IH} I _{OH} = 24mA 24mA
I _{IN}	Maximum Input	5.5		±0.1	±0.1	μΑ	$V_I = V_{CC}$, GND
ICCT	Maximum I _{CC} /Input	5.5	0.6		1.5	mA	$V_I = V_{CC} - 2.1V$
lold	Minimum Dynamic Output Current**	5.5			75	mA	V _{OLD} = 1.65V
IOHD		5.5			- 75	mA	V _{OHD} = 3.85V

^{*} All outputs loaded; thresholds on inputs associated with output under test.

MOTOROLA 2

^{**} Maximum test duration 20ms, one output at a time.

AC CHARACTERISTICS ($V_{CC} = 5.0V \pm 10\%$)

			T _A = 25°C C _L = 50 pF		T _A = -40 to +85°C C _L = 50 pF		
Symbol	Parameter	V _{CC} (V)	Min	Max	Min	Max	Unit
f _{MAX}	Maximum Clock Frequency (50% Duty Cycle)	5.0	110		110		MHz
tPLH, tPHL	Propagation <u>D</u> elay CLK to Q _n , Q _n	5.0	4.0	9.0	4.0	11	ns
tpV	Propagation <u>Delay Variation</u> CLK to Q _n , Q _n (see Note 1)	5.0		3.0		3.0	ns
tps	Propagation Delay Skew (Q _n , Q _n) t _{PHL} Actual – t _{PLH} Actual	5.0		1.0		1.0	ns
tos	Output–to–Output Skew $(Q_n, \overline{Q_n})$ $ t_p Q_n - t_p Q_m $ (see Note 2)	5.0		1.0		1.0	ns
^t rise ^t fall	Rise/Fall Time for Q_n , $\overline{Q_n}$ (0.2 x V _{CC} to 0.8 x V _{CC})	5.0		3.0		4.0	ns

For a given set of conditions (i.e., capacitive load, temperature and V_{CC}) the variation from device to device is guaranteed to be less than or equal to the maximum.
 Where t_p Q_n and t_p Q_m are the actual propagation delays (any combination of HIGH or LOW) for any two separate outputs from a given high transition of CLK.

AC OPERATING REQUIREMENTS

			T _A = 25°C C _L = 50 pF		T _A = -40 to +85°C C _L = 50 pF		
Symbol	Parameter	V _{CC} (V)	Min	Max	Min	Max	Unit
t _W	CLK Pulse Width (HIGH to LOW)	5.0	3.0		3.0		ns
tsu	Minimum Setup Time, HIGH or LOW SRB to Clock	5.0	3.5		3.5		ns
tHD	Minimum Hold Time, HIGH or LOW SRB to Clock	5.0	1.0		1.0		ns

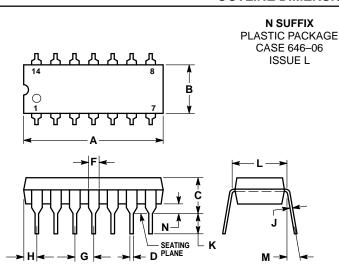
CAPACITANCE

Symbol	Parameter	Тур	Unit	Condition
C _{IN}	Input Capacitance	4.5	pF	V _{CC} = 5.0V
C _{PD}	Power Dissipation Capacitance	30	pF	V _{CC} = 5.0V

3

MOTOROLA

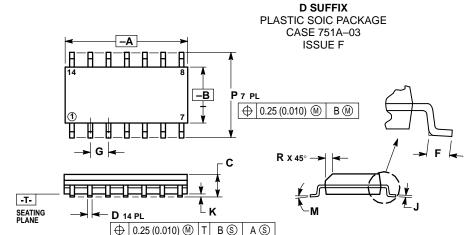
OUTLINE DIMENSIONS



NOTES:

- LEADS WITHIN 0.13 (0.005) RADIUS OF TRUE POSITION AT SEATING PLANE AT MAXIMUM MATERIAL CONDITION.
 DIMENSION L TO CENTER OF LEADS WHEN
- DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
- 3. DIMENSION B DOES NOT INCLUDE MOLD
- FLASH.
 4. ROUNDED CORNERS OPTIONAL.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.715	0.770	18.16	19.56	
В	0.240	0.260	6.10	6.60	
С	0.145	0.185	3.69	4.69	
D	0.015	0.021	0.38	0.53	
F	0.040	0.070	1.02	1.78	
G	0.100	BSC	2.54 BSC		
Н	0.052	0.095	1.32	2.41	
J	0.008	0.015	0.20	0.38	
K	0.115	0.135	2.92	3.43	
L	0.300	BSC	7.62 BSC		
M	0°	10°	0°	10°	
N	0.015	0.039	0.39	1.01	



NOTES

- DIMENSIONING AND TOLERANCING PER ANSI
 Y14 5M 1982
- Y14.5M, 1982.
 2. CONTROLLING DIMENSION: MILLIMETER.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MOLD PROTRUSION.
 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006)
- 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
- 5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIMETERS		INC	HES	
DIM	MIN	MAX	MIN	MAX	
Α	8.55	8.75	0.337	0.344	
В	3.80	4.00	0.150	0.157	
C	1.35	1.75	0.054	0.068	
D	0.35	0.49	0.014	0.019	
F	0.40	1.25	0.016	0.049	
G	1.27	BSC	0.050 BSC		
J	0.19	0.25	0.008	0.009	
K	0.10	0.25	0.004	0.009	
M	0°	7°	0°	7°	
Р	5.80	6.20	0.228	0.244	
R	0.25	0.50	0.010	0.019	

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How to reach us:

USA/EUROPE: Motorola Literature Distribution; P.O. Box 20912; Phoenix, Arizona 85036. 1–800–441–2447

MFAX: RMFAX0@email.sps.mot.com –TOUCHTONE (602) 244–6609 INTERNET: http://Design=NET.com

JAPAN: Nippon Motorola Ltd.; Tatsumi-SPD-JLDC, Toshikatsu Otsuki, 6F Seibu-Butsuryu-Center, 3–14–2 Tatsumi Koto-Ku, Tokyo 135, Japan. 03–3521–8315

HONG KONG: Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park, 51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852–26629298



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