


## Pin Descriptions

| Pin Names | Description |
| :--- | :--- |
| $A_{0}-A_{15}$ | Data Register A Inputs/3-STATE Outputs |
| $B_{0}-B_{15}$ | Data Register B Inputs/3-STATE Outputs |
| CPAB $_{n}$, CPBA $_{n}$ | Clock Pulse Inputs |
| $\mathrm{SAB}_{n}, \mathrm{SBA}_{n}$ | Select Inputs |
| $\overline{O E}_{1}, \overline{O E}_{2}$ | Output Enable Inputs |
| $\mathrm{DIR}_{n}$ | Direction Control Inputs |

Truth Table(Note 1)


## Functional Description

In the transceiver mode, data present at the HIGH impedance port may be stored in either the A or B register or both. The select $\left(\mathrm{SAB}_{\mathrm{n}}, \mathrm{SBA}_{\mathrm{n}}\right)$ controls can multiplex stored and real-time. The examples shown below demonstrate the four fundamental bus-management functions that can be performed

## Real-Time Transfer

Bus B to Bus A


## $\overline{O E}$ DIR CPAB CPBA SAB SBA

$L \quad L \quad X \quad X \quad X \quad L$

Transfer Storage
Data to A or B

$\overline{O E}$ DIR CPAB CPBA SAB SBA
$\begin{array}{cccccc}L & L & X & H \text { or } L & X & H \\ L & H & H & \text { or } & X & H\end{array}$

The direction control ( $\mathrm{DIR}_{n}$ ) determines which bus will receive data when $\overline{\mathrm{OE}}_{n}$ is LOW. In the isolation mode $\left(\overline{\mathrm{OE}}_{n}\right.$ HIGH), A data may be stored in one register and/or B data may be stored in the other register. When an output function is disabled, the input function is still enabled and may be used to store and transmit data. Only one of the two busses, A or B, may be driven at a time.


Storage


| $\overline{\text { OE }}$ | DIR | CPAB | CPBA | SAB | SBA |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L | $H$ | $\sim$ | $X$ | $L$ | $X$ |
| $L$ | $L$ | $X$ | $\sim$ | $X$ | $L$ |
| $H$ | $X$ | $\sim$ | $X$ | $X$ | $X$ |
| $H$ | $X$ | $X$ | $\sim$ | $X$ | $X$ |



| Absolute Maximum Ratings(Note 2) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Parameter | Value | Conditions |  | Units |
| $\mathrm{V}_{\text {CC }}$ | Supply Voltage | -0.5 to +4.6 |  |  | V |
| $\mathrm{V}_{1}$ | DC Input Voltage | -0.5 to +7.0 |  |  | V |
| $\mathrm{V}_{\mathrm{O}}$ | DC Output Voltage | -0.5 to +7.0 | Output in 3-STATE |  | V |
|  |  | -0.5 to +7.0 | Output in HIGH or LOW State (Note 3) |  | V |
| $\mathrm{I}_{\mathrm{K}}$ | DC Input Diode Current | -50 | $V_{1}<$ GND |  | mA |
| $\mathrm{I}_{\text {OK }}$ | DC Output Diode Current | -50 | $\mathrm{V}_{\mathrm{O}}<\mathrm{GND}$ |  | mA |
| $\mathrm{I}_{0}$ | DC Output Current | 64 | $\mathrm{V}_{\mathrm{O}}>\mathrm{V}_{\text {CC }}$ Output at HIGH State |  | mA |
|  |  | 128 | $\mathrm{V}_{\mathrm{O}}>\mathrm{V}_{\text {CC }}$ Output at LOW State |  |  |
| $\mathrm{I}_{\mathrm{CC}}$ | DC Supply Current per Supply Pin | $\pm 64$ |  |  | mA |
| $\mathrm{I}_{\text {GND }}$ | DC Ground Current per Ground Pin | $\pm 128$ |  |  | mA |
| TSTG | Storage Temperature | -65 to +150 |  |  | ${ }^{\circ} \mathrm{C}$ |
| Recommended Operating Conditions |  |  |  |  |  |
| Symbol | Parameter |  | Min | Max | Units |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply Voltage |  | 2.7 | 3.6 | V |
| $V_{1}$ | Input Voltage |  | 0 | 5.5 | V |
| IOH | HIGH-Level Output Current |  |  | -32 | mA |
| $\mathrm{IOL}^{\text {l }}$ | LOW-Level Output Current |  |  | 64 |  |
| $\mathrm{T}_{\mathrm{A}}$ | Free-Air Operating Temperature |  | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |
| $\Delta \mathrm{t} / \Delta \mathrm{V}$ | Input Edge Rate, $\mathrm{V}_{\mathrm{IN}}=0.8 \mathrm{~V}-2.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}=3.0 \mathrm{~V}$ |  | 0 | 10 | ns/V |
| Note 2: Absolute Maximum continuous ratings are those values beyond which damage to the device may occur. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation under absolute maximum rated conditions is not implied. <br> Note 3: $\mathrm{I}_{\mathrm{O}}$ Absolute Maximum Rating must be observed. |  |  |  |  |  |


| Symbol | Parameter | $\mathrm{V}_{\mathrm{cc}}$ <br> (V) | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | Units | Conditions |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max |  |  |  |
| $\mathrm{V}_{\mathrm{IK}}$ | Input Clamp Diode Voltage | 2.7 |  | -1.2 | V | $\mathrm{I}_{\mathrm{I}}=-18 \mathrm{~mA}$ |  |
| $\mathrm{V}_{\text {IH }}$ | Input HIGH Voltage | 2.7-3.6 | 2.0 |  | V | $\begin{aligned} & \mathrm{V}_{\mathrm{O}} \leq 0.1 \mathrm{~V} \text { or } \\ & \mathrm{V}_{\mathrm{O}} \geq \mathrm{V}_{\mathrm{CC}}-0.1 \mathrm{~V} \end{aligned}$ |  |
| $\overline{\mathrm{V}} \mathrm{IL}$ | Input LOW Voltage | 2.7-3.6 |  | 0.8 |  |  |  |
| $\mathrm{V}_{\mathrm{OH}}$ | Output HIGH Voltage | 2.7-3.6 | $\mathrm{V}_{\mathrm{CC}}-0.2$ |  | V | $\mathrm{I}_{\mathrm{OH}}=-100 \mu \mathrm{~A}$ |  |
|  |  | 2.7 | 2.4 |  | V | $\mathrm{I}_{\mathrm{OH}}=-8 \mathrm{~mA}$ |  |
|  |  | 3.0 | 2.0 |  | V | $\mathrm{I}_{\mathrm{OH}}=-32 \mathrm{~mA}$ |  |
| $\mathrm{V}_{\mathrm{OL}}$ | Output LOW Voltage | 2.7 |  | 0.2 | V | $\mathrm{l}_{\mathrm{OL}}=100 \mu \mathrm{~A}$ |  |
|  |  | 2.7 |  | 0.5 | V | $\mathrm{I}_{\mathrm{OL}}=24 \mathrm{~mA}$ |  |
|  |  | 3.0 |  | 0.4 | V | $\mathrm{I}_{\mathrm{OL}}=16 \mathrm{~mA}$ |  |
|  |  | 3.0 |  | 0.5 | V | $\mathrm{I}_{\mathrm{OL}}=32 \mathrm{~mA}$ |  |
|  |  | 3.0 |  | 0.55 | V | $\mathrm{I}_{\mathrm{OL}}=64 \mathrm{~mA}$ |  |
| $I_{\text {(HOLD })}$ | Bushold Input Minimum Drive | 3.0 | 75 |  | $\mu \mathrm{A}$ | $\mathrm{V}_{1}=0.8 \mathrm{~V}$ |  |
|  |  |  | -75 |  | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{I}}=2.0 \mathrm{~V}$ |  |
| $\overline{I_{(O D)}}$ | Bushold Input Over-Drive Current to Change State | 3.0 | 500 |  | $\mu \mathrm{A}$ | (Note 4) |  |
|  |  |  | -500 |  | $\mu \mathrm{A}$ | (Note 5) |  |
| $I$ | Input CurrentControl Pins <br> Data Pins | 3.6 |  | 10 | $\mu \mathrm{A}$ | $\mathrm{V}_{1}=5.5 \mathrm{~V}$ |  |
|  |  | 3.6 |  | $\pm 1$ | $\mu \mathrm{A}$ | $\mathrm{V}_{1}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CC}}$ |  |
|  |  | 3.6 |  | -5 | $\mu \mathrm{A}$ | $\mathrm{V}_{1}=0 \mathrm{~V}$ |  |
|  |  |  |  | 1 | $\mu \mathrm{A}$ | $\mathrm{V}_{1}=\mathrm{V}_{\text {CC }}$ |  |
| IOFF | Power Off Leakage Current | 0 |  | $\pm 100$ | $\mu \mathrm{A}$ | $0 \mathrm{~V} \leq \mathrm{V}_{1}$ or $\mathrm{V}_{\mathrm{O}} \leq 5.5 \mathrm{~V}$ |  |
| $\mathrm{I}_{\text {PU/PD }}$ | Power Up/Down 3-STATE Output Current | 0-1.5V |  | $\pm 100$ | $\mu \mathrm{A}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{O}}=0.5 \mathrm{~V} \text { to } 3.0 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{I}}=\mathrm{GND} \text { or } \mathrm{V}_{\mathrm{CC}} \end{aligned}$ |  |
| IozL | 3-STATE Output Leakage Current | 3.6 |  | -5 | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{O}}=0.0 \mathrm{~V}$ |  |
| $\mathrm{I}_{\text {OZH }}$ | 3-STATE Output Leakage Current | 3.6 |  | 5 | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{O}}=3.6 \mathrm{~V}$ |  |
| $\mathrm{lozH}^{+}$ | 3-STATE Output Leakage Current | 3.6 |  | 10 | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{CC}}<\mathrm{V}_{\mathrm{O}} \leq 5.5 \mathrm{~V}$ |  |
| $\mathrm{I}_{\text {CCH }}$ | Power Supply Current | 3.6 |  | 0.19 | mA | Outputs HIGH |  |
| ${ }^{\text {ICCL }}$ | Power Supply Current | 3.6 |  | 5 | mA | Outputs LOW |  |
| $\mathrm{I}_{\text {CCZ }}$ | Power Supply Current | 3.6 |  | 0.19 | mA | Outputs Disabled |  |
| $\mathrm{ICCZ}^{+}$ | Power Supply Current | 3.6 |  | 0.19 | mA | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}} \leq \mathrm{V}_{\mathrm{O}} \leq 5.5 \mathrm{~V}, \\ & \text { Outputs Disabled } \end{aligned}$ |  |
| $\overline{\Delta l}^{\text {CC }}$ | Increase in Power Supply Current (Note 6) | 3.6 |  | 0.2 | mA | One Input at $\mathrm{V}_{\mathrm{CC}}-0.6 \mathrm{~V}$ Other Inputs at $\mathrm{V}_{\mathrm{CC}}$ or GND |  |
| Note 4: An external driver must source at least the specified current to switch from LOW-to-HIGH. <br> Note 5: An external driver must sink at least the specified current to switch from HIGH-to-LOW. <br> Note 6: This is the increase in supply current for each input that is at the specified voltage level rather than $\mathrm{V}_{\mathrm{CC}}$ or <br> Dynamic Switching Characteristics (Note 7) |  |  |  |  |  |  |  |
| Symbol | Parameter | $\mathrm{V}_{\mathrm{cc}}$ <br> (V) | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | Units | Conditions$\begin{aligned} & \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{L}}=500 \Omega \end{aligned}$ |
|  |  |  | Min | Typ | Max |  |  |
| $\mathrm{V}_{\text {OLP }}$ | Quiet Output Maximum Dynamic $\mathrm{V}_{\mathrm{OL}}$ | 3.3 |  | 0.8 |  | V | (Note 8) |
| $\mathrm{V}_{\text {OLV }}$ | Quiet Output Minimum Dynamic $\mathrm{V}_{\mathrm{OL}}$ | 3.3 |  | -0.8 |  | V | (Note 8) |
| Note 7: Characterized in SSOP package. Guaranteed parameter, but not tested. <br> Note 8: Max number of outputs defined as ( n ). $\mathrm{n}-1$ data inputs are driven 0 V to 3 V . Output under test held LOW. |  |  |  |  |  |  |  |

## AC Electrical Characteristics

| Symbol | Parameter |  | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C} \\ \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=500 \Omega \end{gathered}$ |  |  |  | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\mathrm{V}_{\mathrm{CC}}=3.3 \pm 0.3 \mathrm{~V}$ |  | $\mathrm{V}_{\mathrm{CC}}=2.7 \mathrm{~V}$ |  |  |
|  |  |  | Min | Max | Min | Max |  |
| $\mathrm{f}_{\text {MAX }}$ | Maximum Clock Frequency |  | 150 |  | 150 |  | MHz |
| $\begin{aligned} & \hline \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \end{aligned}$ | Propagation Delay CPAB or CPBA to A or B |  | $\begin{aligned} & 1.3 \\ & 1.3 \end{aligned}$ | $\begin{aligned} & 5.4 \\ & 5.2 \end{aligned}$ | $\begin{aligned} & 1.3 \\ & 1.3 \end{aligned}$ | $\begin{aligned} & 5.9 \\ & 5.8 \end{aligned}$ | ns |
| $\begin{aligned} & \hline \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \end{aligned}$ | Propagation Delay Data to A or B |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 4.4 \\ & 4.6 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 4.7 \\ & 5.1 \end{aligned}$ | ns |
| $\begin{aligned} & \mathrm{t}_{\mathrm{PLH}} \\ & \mathrm{t}_{\mathrm{PHL}} \end{aligned}$ | Propagation Delay SBA or SAB to A or B |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 4.6 \\ & 4.8 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.4 \\ & 5.6 \end{aligned}$ | ns |
| $\begin{aligned} & \hline \mathrm{t}_{\mathrm{PZH}} \\ & \mathrm{t}_{\mathrm{PZL}} \end{aligned}$ | Output Enable Time $\overline{\mathrm{OE}}$ to A or B |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 4.7 \\ & 5.1 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.4 \\ & 6.0 \end{aligned}$ | ns |
| $\begin{aligned} & \overline{t_{\text {PHZ }}} \\ & t_{\text {PLZ }} \end{aligned}$ | Output Disable Time $\overline{\mathrm{OE}}$ to A or B |  | $\begin{aligned} & 2.0 \\ & 2.0 \end{aligned}$ | $\begin{aligned} & 5.6 \\ & 5.4 \end{aligned}$ | $\begin{aligned} & \hline 2.0 \\ & 2.0 \end{aligned}$ | $\begin{aligned} & 6.1 \\ & 6.1 \end{aligned}$ | ns |
| $\begin{aligned} & \hline \mathrm{t}_{\mathrm{PZH}} \\ & \mathrm{t}_{\mathrm{PZL}} \end{aligned}$ | Output Enable Time DIR to A or B |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & \hline 4.9 \\ & 5.4 \end{aligned}$ | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | $\begin{aligned} & 5.4 \\ & 6.4 \end{aligned}$ | ns |
| $\begin{aligned} & \hline \mathrm{t}_{\mathrm{PHZ}} \\ & \mathrm{t}_{\mathrm{PLZ}} \end{aligned}$ | Output Disable Time DIR to A or B |  | $\begin{aligned} & 1.5 \\ & 1.5 \end{aligned}$ | $\begin{aligned} & 6.4 \\ & 5.4 \end{aligned}$ | $\begin{aligned} & 1.5 \\ & 1.5 \end{aligned}$ | $\begin{aligned} & 7.1 \\ & 5.9 \end{aligned}$ | ns |
| $\mathrm{t}_{\mathrm{W}}$ | Pulse Duration CPAB or CPBA HIGH or LOW |  | 3.3 |  | 3.3 |  | ns |
| $\mathrm{t}_{\mathrm{S}}$ | Setup Time | A or B before CPAB or CPBA, Data HIGH | 1.2 |  | 1.5 |  | ns |
|  |  | A or B before CPAB or CPBA, Data LOW | 2.0 |  | 2.8 |  |  |
| $\mathrm{t}_{\mathrm{H}}$ | Hold Time | A or B after CPAB or CPBA, Data HIGH | 0.5 |  | 0.0 |  | ns |
|  |  | A or B after CPAB or CPBA, Data LOW | 0.5 |  | 0.5 |  |  |
| toshL <br> $t^{\text {OSLH}}$ | Output to Output Skew (Note 9) |  |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ |  | $\begin{aligned} & 1.0 \\ & 1.0 \end{aligned}$ | ns |

Note 9: Skew is defined as the absolute value of the difference between the actual propagation delay for any two separate outputs of the same device. The specification applies to any outputs switching in the same direction, either HIGH-to-LOW ( $\mathrm{t}_{\mathrm{OSHL}}$ ) or LOW-to-HIGH (t $\mathrm{OSSL}^{\text {OSH }}$ ).

Capacitance (Note 10)

| Symbol | Parameter | Conditions | Typical | Units |
| :--- | :--- | :--- | :---: | :---: |
| $\mathrm{C}_{\mathrm{IN}}$ | Input Capacitance | $\mathrm{V}_{\mathrm{CC}}=$ Open, $\mathrm{V}_{\mathrm{I}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CC}}$ | 4 | pF |
| $\mathrm{C}_{/ \mathrm{O}}$ | Input/Output Capacitance | $\mathrm{V}_{\mathrm{CC}}=3.0 \mathrm{~V}, \mathrm{~V}_{\mathrm{O}}=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{CC}}$ | 8 | pF |

Note 10: Capacitance is measured at frequency $\mathrm{f}=1 \mathrm{MHz}$, per MIL-STD-883, Method 3012.


Physical Dimensions inches (millimeters) unless otherwise noted (Continued)


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